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Energy balance at the soil atmospheric interface

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Soil atmospheric interactions play an important role within the thermal energy balance and seasonal temperature variations of the ground. This paper presents a formulation for the surface boundary conditions related to interactions between soil and atmosphere. The boundary condition formulated considers heat flow at the soil–atmosphere interface through mechanisms of shortwave radiation, long-wave radiation, sensible radiation and latent heat radiation. The effects of surface moisture flux on energy balance at the interface are explicitly included in the formulation. The developed boundary condition has been implemented in a numerical model for coupled thermal, hydraulic and mechanical behaviour of unsaturated soils. The evaporation component of the model is tested, and the results are compared with data from an experimental study at the surface of an area of agricultural land reported in the literature. The results of modelling have been found to compare favourably with the reported data set. The formulation developed for the soil atmospheric boundary condition allows climatic variables, including solar radiation, ambient air temperature, relative humidity, wind speed, rainfall and evaporation, to be incorporated in the long-term analysis of energy balance. This also enables a further detailed inspection of the climate's role in ground thermal behaviour of ground source heat systems.

Notation

A	sum of the heat convection components
A_0	annual amplitude of the surface soil temperature
C_{cloud}	fractional cloud cover coefficient
C_p	specific heat capacity of the ground
D_h	thermal diffusivity
d	damping depth
E	evaporation flux
E_a	actual evaporation flux
H	total radiation heat flux absorbed or emitted at the soil surface
$H_{\text{SW}}^{\text{Absorbed}}$	adsorbed shortwave radiation flux
$H_{\text{LW}}^{\text{Emitted}}$	radiation flux emitted from the ground surface
$H_{\text{LW}}^{\text{Net}}$	net long-wave radiation flux
H_c	heat storage capacity
H_{LE}	latent heat flux
H_{SN}	sensible heat flux
h	relative humidity of the ground
h_{air}	air relative humidity at the ground surface
k	von Karman constant

L	latent heat of vaporisation
P	precipitation mass flux
Q_m	net mass flux at the ground surface
q	specific humidity of soil
q_{air}	specific humidity of air
R	run-off
r_a	aerodynamic resistance
T	absolute temperature of soil
$T(z, t)$	soil temperature at time t and depth z
T_a	constant ground temperature
T_{air}	absolute temperature of the air adjacent to the ground surface
T_r	reference temperature
t	time
t_0	lag time from arbitrary start date to the occurrence of the minimum soil temperature in a year
u_z	wind speed at the reference elevation
v_a	velocity of air
v_l	velocity of liquid
v_v	velocity of vapour

z	depth beneath the ground surface
z_0	surface roughness
δV	incremental volume of the soil
ε_{LW}^A	long-wave emissivity of the air at ground level
ε_{LW}	long-wave emissivity
ε_{SW}	shortwave reflection factor associated with the ground surface type
λ_T	thermal conductivity
ρ_a	air density
ρ_l	density of liquid water
ρ_v	density of water vapour
σ	Stefan-Boltzmann constant
ω	$2\pi/365$
∇	gradient operator

Introduction

Ground source heat pump (GSHP) systems are among the low-entropy geothermal energy extraction methods which allow energy extraction from the shallow depth of the Earth's crust in order to provide space heating and/or cooling (Sanner *et al.*, 2003). The ground temperature at shallow depths is predominantly a function of the upper surface processes – that is, climatic conditions such as solar radiation and ambient air temperature. At greater depths, temperature increases with depth according to the geothermal gradient that is determined by the vertical heat flow in the Earth and the thermal properties of local geology (e.g. Busby *et al.*, 2011). The ground located in closest proximity to the surface is subject to the greatest changes due to climatic variations and atmospheric conditions. Depending on the local climate and ground conditions, the annual temperature variations can typically occur within only the upper 10 m of ground depth (e.g. Busby *et al.*, 2011). Beyond this depth, there are limited ground temperature variations within the shallow geothermal region.

Within the scope of closed-loop ground source heat systems, various configurations exist which can be employed to exchange heat with the ground. The ground-loop types can be broadly split into two categories according to their orientation, namely vertical and horizontal ground loops. Vertical systems are conventionally installed within boreholes with depths typically ranging between 20 and 200 m (Yang *et al.*, 2010). Horizontal systems, on the other hand, typically range in depth between 1 and 2 m (Wu *et al.*, 2010). Figure 1 presents a schematic diagram of a horizontal ground source heat system where the buried ground loop is shown in the cutaway section.

Analysis of GSHP systems requires consideration of two boundary conditions including: (a) the ground surface boundary and (b) ground-loop boundary. The ground surface boundary represents the heat and mass exchange at the soil atmospheric interface. The ground-loop boundary represents the ground interaction with the buried ground-loop pipe surface where the heat is exchanged with the ground by way of the heat pump system. Figure 2 presents a schematic diagram of the boundary conditions of a horizontal ground source heat system.

Figure 1. Schematic diagram of a horizontal ground source heat system

The proximity of horizontal ground loops to the ground surface positions this type of system within a ground depth that is subjected to annual temperature variations (Leong *et al.*, 1998). The ground thermal behaviour is a function of the thermal energy extracted from/injected into the ground, climatic and surface conditions and ground properties. The interactions between the ground and the atmosphere can play an important role in the surface energy balance and can affect the seasonal ground temperature variations (Deardorff, 1978). This can affect thermal, hydraulic and mechanical behaviour in various ways (e.g. Vardon, 2015). The seasonal ground temperature variations with depth have been extensively studied (e.g. De Vries and Van Wijk, 1966). It has been shown that the thermal behaviour of the ground and interactions with the atmosphere can be influenced by the ground surface vegetation coverage (Gonzalez *et al.*, 2012).

A number of investigations into the ground thermal behaviour of GSHP systems have been reported for a range of ground conditions – for example arid ground in Asia (Esen *et al.*, 2007), North America (Mei, 1986) and the UK (Wu *et al.*, 2011). Wu *et al.* (2011) presented a study on thermal performance of a horizontal system and ground temperature distributions considering fixed ambient air temperatures and fixed wind speeds. It was reported that an intermittent cycle has led to a reduced system performance for all ambient air temperature and wind speed cases. Esen *et al.* (2007) studied the efficiency of a horizontal ground source heat system in Turkey during the cooling mode operation (i.e. storing heat in the ground) which was located at 2 m depth. By using an analytical model, it was shown that the efficiency of the system under cooling mode had decreased from 56 to 46% when the ambient air temperature increased from 0 to 25°C. The majority of investigations reported have considered a simplified form of the description of the energy balance at the ground surface (i.e. as a fixed temperature boundary condition based on annual ambient air temperature variations). An extensive experimental investigation of a horizontal ground source heat system and ground temperature

Figure 2. Schematic diagram of the ground surface boundary and ground-loop boundary in a horizontal ground source heat system

response has also been presented by Thomas *et al.* (2013), Hepburn (2014) and Hepburn *et al.* (2016). This investigation presents the soil thermal response in relation to seasonal variations and heat extraction.

The so-called energy balance equation has been reported to provide a prediction of annual and diurnal variations in ground temperature (Deardorff, 1978). The energy balance equation essentially calculates the overall radiant energy being absorbed or emitted by the thin upper layer of the ground surface. This paper revisits the energy balance at the ground atmospheric interface with the aim to provide a comprehensive description of the ground boundary condition for ground source heat system studies. A formulation for the surface boundary conditions related to thermal and hydraulic interactions between soil and atmosphere is presented in this paper. The boundary condition developed considers the heat flow at the interface between soil and atmosphere through the mechanisms of shortwave radiation, long-wave radiation, sensible radiation and latent heat radiation. In addition, the effects of surface moisture flux on energy balance at the interface are explicitly considered in the coupled formulation proposed. The developed boundary condition has been

implemented in a numerical model for coupled thermal, hydraulic and mechanical behaviour of unsaturated soils (e.g. Thomas and He, 1995). The accuracy of the surface boundary condition and the implementation of the model are tested against a series of experimental data.

Energy balance at the soil atmospheric interface

The surface boundary condition presented here considers the heat and moisture flow at the soil atmospheric interface. The energy balance equation is used to provide a description of the annual and diurnal ground temperature variations (Deardorff, 1978). Four major mechanisms of heat exchange between the ground surface and atmosphere are considered, given as (van Wijk, 1966)

- shortwave heat radiation
- long-wave heat radiation
- sensible heat radiation
- latent heat radiation.

Figure 3 presents a schematic diagram of the heat exchange mechanisms considered at the soil–atmosphere interface.

Figure 3. Major mechanisms of energy exchange at the soil–atmosphere interface

A general form of the energy balance equation can be presented as (van Wijk, 1966)

$$1. \quad H = H_{SW}^{Absorbed} - (H_{LW}^{Net} + H_{SN} + H_{LE})$$

where H is the total radiation heat flux absorbed or emitted at the soil surface. $H_{SW}^{Absorbed}$ is the adsorbed shortwave radiation flux, H_{LW}^{Net} is the net long-wave radiation flux, H_{SN} represents the sensible heat flux and H_{LE} is the latent heat flux. It is noted that the unit of heat flux used is watts per square metre.

The following sections provide the details of the individual components of the surface energy balance equation described in Equation 1.

Shortwave radiation

Shortwave radiation is a combination of direct and diffused solar radiation striking the Earth's surface. The diffuse radiation is primarily caused by clouds, dust and molecules scattering in the atmosphere (van Wijk and Scholte Ubing, 1966). This is commonly referred to as *shortwave radiation*, as the majority of the associated radiation has wavelengths within the infrared and visible bands of the electromagnetic spectrum (van Wijk and Scholte Ubing, 1966). The total shortwave flux striking the Earth's surface varies on a diurnal and annual basis, depending on the solar inclination and climatic conditions. A considerable fraction of the shortwave flux that reaches the Earth's surface is reflected. The exact proportion of the radiation reflected depends on the ground surface coverage and reflection properties. The fraction of the shortwave radiation flux absorbed at the surface can be presented as (Deardorff, 1978)

$$2. \quad H_{SW}^{Absorbed} = \varepsilon_{SW} H_{SW}$$

where $H_{SW}^{Absorbed}$ is the heat flux associated with the absorbed shortwave radiation and ε_{SW} is the shortwave reflection factor associated with the ground surface type.

In order to calculate the shortwave radiation component, a representative value of shortwave radiation is required. Values either can be obtained by way of monitoring, using appropriate historical records, or can be approximated using irradiance models. A number of theoretical and empirical irradiance models have also been proposed (e.g. van Wijk and Scholte Ubing, 1966; Woodward *et al.*, 2001). The shortwave reflection factor varies for different surfaces and recommended values have been provided in the literature (e.g. van Wijk and Scholte Ubing, 1966).

Net long-wave radiation

The net long-wave radiation at the ground surface can be described as a combination of long-wave radiation being emitted from the ground and long-wave radiation being absorbed from the

atmosphere. Within the context of this formulation, the absorbed radiation is referred to as the long-wave radiation passing from the atmosphere towards the Earth's surface, with the emitted radiation travelling in the opposite direction. This can be expressed as

$$3. \quad H_{LW}^{Net} = H_{SW}^{Absorbed} - H_{LW}^{Emitted}$$

where $H_{SW}^{Absorbed}$ is the radiation flux absorbed at the ground surface and $H_{LW}^{Emitted}$ is the radiation flux emitted from the ground surface.

The amount of long-wave radiation absorbed from the atmosphere is dependent on cloud formation. The proposed approaches commonly incorporate coefficients which are specific to local regions. A general approach was formulated by Imberger and Patterson (1981) to calculate the long-wave radiation being absorbed at the ground surface from the atmosphere, given as

$$4. \quad H_{SW}^{Absorbed} = \varepsilon_{LW}^4 \sigma T_{air}^4 (1 + 0.17 C_{cloud}^2)$$

where ε_{LW}^4 is the long-wave emissivity of the air at ground level (non-dimensional), C_{cloud} is the fractional cloud cover coefficient ($C_{cloud} = 0$ for clear sky and $C_{cloud} = 1$ for totally overcast) and T_{air} is the absolute temperature of the air adjacent to the ground surface.

The long-wave radiation being emitted by a body can be calculated using Stefan–Boltzmann's law (Woodward *et al.*, 2001). The Stefan–Boltzmann law states that the energy emitted by a body is directly proportional to the fourth power of its absolute temperature, given as (Lewis *et al.*, 2004)

$$5. \quad H_{LW}^{Emitted} = \varepsilon_{LW} \sigma T^4$$

where ε_{LW} is the long-wave emissivity of the body (dimensionless) and σ is the Stefan–Boltzmann constant ($5.67 \times 10^{-8} \text{ W/(m}^2 \text{ K}^4)$). T represents the absolute temperature.

Sensible heat radiation

Sensible heat radiation can be defined as the heat exchange within a thermodynamic system that has a sole effect of temperature variation on the constituent bodies (i.e. not energy associated with a phase change). Sensible heat radiation is a function of both thermal conduction and convection. With respect to the ground surface boundary, the sensible heat flux is (Deardorff, 1978)

$$6. \quad H_{SN} = \frac{\rho_a C_p}{r_a} (T - T_{air})$$

where ρ_a is the air density (kg/m^3), C_p is the ground specific heat capacity (J/(kg K)) and r_a is the aerodynamic resistance.

The aerodynamic resistance accounts for the mixing and turbulence of the air above the evaporating surface (Fuchs and Tanner, 1967). For the formulation of the surface boundary condition presented here, the following transition function proposed by Sverdrup (1946) is applied

$$7. \quad r_a = \frac{k^2 u_z}{[\ln(z/z_0)]^2}$$

where k is the von Karman constant (equal to 0.41) and u_z is the wind speed at the reference elevation. z_0 is the surface roughness, which allows the surface texture (e.g. grass and concrete) to be considered when calculating the mixing characteristics of the air immediately above the ground surface. When considering the effect of the surface boundary, this feature can be important in the recharge of the ground.

The relationship presented in Equation 6 is essentially a form of Fourier's law of conduction, which forms the foundation of one-dimensional heat conduction (Deardorff, 1978). The components of ρ_a , C_p and r_a provide a modified thermal conductivity value, thereby incorporating a convective component within the equation (Deardorff, 1978).

Latent heat radiation

Latent heat radiation can be defined as the absorption or release of energy within a thermodynamic system that occurs without a change in temperature (i.e. energy related to molecule changes of state). In the context of the surface boundary condition, this is primarily linked to the evaporation of water from the upper regions of the ground surface.

The latent heat flux due to evaporation is calculated as follows

$$8. \quad H_{LE} = LE$$

where L is the latent heat of vaporisation (kJ/kg) and E is evaporation flux.

The water vapour flux presented in Equation 7 is the moisture flux at the ground surface, which represents the evaporation from the soil surface. The evaporation process is affected and controlled by atmospheric, surface and ground factors (Deardorff, 1978; Fuchs and Tanner, 1967). The rate of evaporation is greatly influenced by the moisture content of soil at the ground surface, linking the boundary to the moisture transfer in the soil. Based on the calculations of Dalton's mass transfer formula, the evaporation rate can be given as (Deardorff, 1978)

$$9. \quad E = \rho_a r_a (q - q_{\text{air}})$$

where q is the specific humidity of the soil (mass of water vapour in a unit mass of moist air) at the ground surface and q_{air} is the specific humidity of air.

Equation 9, with substitution of Equation 6 and energy balance (without shortwave and long-wave radiation) can yield the Penman–Monteith equation (Monteith, 1965) that includes the effects of the vegetation bulked on the aerodynamic resistance. Maintaining the separation of these terms makes easier substitution into a coupled model, with each of the boundary conditions separately addressed.

The value of the rate of evaporation (E) calculated by Equation 8 is equal to the so-called potential evaporation. The term 'potential evaporation' can be described as the upper limit or the maximum rate of evaporation from a surface (Barton, 1979). With respect to the evaporation from soil, potential evaporation remains a valid approximation of the overall evaporation provided that there is a constant supply of available water at the ground surface – that is, when the ground surface is saturated (Wilson *et al.*, 1997). As the surface of soil enters the unsaturated state, the availability of water depends on the water retention characteristics of the soil. Wilson *et al.* (1997) presented a modified Dalton's mass transfer equation to predict the evaporative rates from unsaturated soil surfaces

$$10. \quad E_a = E \left(\frac{h - h_{\text{air}}}{1 - h_{\text{air}}} \right)$$

where E_a is the actual evaporation flux, h is the relative humidity of the ground surface and h_{air} is the relative humidity of air at the ground surface.

The latent heat flux due to evaporation can therefore be expanded as follows

$$11. \quad H_{LE} = L \rho_a r_a (q - q_{\text{air}}) \left(\frac{h - h_{\text{air}}}{1 - h_{\text{air}}} \right)$$

Surface moisture flux

In order to model the coupled heat and mass boundary condition, a representative mass boundary describing hydrological processes at the ground surface is presented. Assuming that the net moisture flux at the surface boundary is a function of hydrological process only, the following equation can be applied to calculate the ground surface moisture flux (Fredlund *et al.*, 2011)

$$12. \quad Q_m = P - E_a - R$$

where Q_m is the net mass flux at the ground surface (kg/m^2), P is the precipitation mass flux, E_a is the evaporation mass flux according to Equation 10 and R is the run-off.

For highly compressible soils, consolidation processes should also be taken into account; see for example Vardon *et al.* (2014). However, it would be unlikely that such soils would be selected for use for GSHP systems.

Equation 12 presents the surface moisture exchange in terms of liquid and vapour phases. Precipitation data are available for specific geographical regions; therefore, representative values can be obtained and prescribed in most cases.

Numerical implementation and model development

The surface boundary conditions described in the previous section have been implemented within an existing numerical model of coupled thermal, hydraulic and mechanical behaviour of unsaturated soils (Thomas and He, 1995). The model considers the heat and moisture flow in unsaturated soils.

The governing equation of moisture flow is based on the principle of mass conservation and follows the formulation provided by Thomas and He (1995). This can be expressed as

$$13. \quad \frac{\partial}{\partial t} (\rho_l \theta_l \delta V) + \frac{\partial}{\partial t} (\rho_v \theta_a \delta V) = -\delta V \nabla(\rho_l \mathbf{v}_l) - \delta V \nabla(\rho_v \mathbf{v}_v) - \delta V \nabla(\rho_v \mathbf{v}_a)$$

where t is time (s), ρ_l is the density of liquid water (kg/m^3), θ_l is the volumetric water content, ρ_v is the density of water vapour (kg/m^3) and θ_a is the volumetric air content. ∇ is the gradient operator, and δV is the incremental volume of the soil. $\mathbf{v}_l$ is the velocity of liquid (m/s), $\mathbf{v}_v$ is the velocity of vapour (m/s) and $\mathbf{v}_a$ is the velocity of air (m/s).

The governing equation of heat transfer is based on the energy conservation law in unsaturated porous media (Thomas and He, 1995). Based on the formulation presented Thomas and He (1995), the governing equation of heat transfer can be presented as

$$14. \quad \frac{\partial}{\partial t} [H_c (T - T_r)] = -\delta V \nabla [-\lambda_T \nabla T + A(T - T_r) + L(\rho_l \mathbf{v}_v + \rho_v \mathbf{v}_a)]$$

where H_c is the heat storage capacity (J/K), T_r stands for the reference temperature (K), λ_T is the thermal conductivity (W/(m K)) and A stands for the sum of the heat convection components.

Details of the expanded governing equations for moisture and heat transfer presented in Equations 13 and 14 can be found in Thomas and He (1995).

The formulation of water flow has been implemented within an existing numerical model (Compass) developed at the

Geoenvironmental Research Centre, Cardiff University, which is based on finite-element and finite-difference methods (Sedighi *et al.* 2016; Thomas and He, 1995; Thomas *et al.*, 2012). The Galerkin weighted residual method has been adopted, by which the spatial discretisation is developed and the temporal discretisation is achieved by applying an implicit finite-difference algorithm (Thomas and He, 1995). The model has been extensively tested and applied to study the coupled behaviour of unsaturated soils (e.g. Thomas *et al.*, 2012). Details of the numerical formulation and computational aspects have been discussed in previous publications (e.g. Thomas and He, 1995); therefore, the details are not repeated here.

Implementation of the developed surface boundary formulations within the numerical model is presented here. Figure 4 shows a schematic diagram of the ground surface boundary and a model domain discretised into a number of elements. Based on the series of theoretical formulations provided in the section titled 'Energy balance at the soil atmospheric interface', the climatic variables that are required to model the surface are

- ambient air temperature
- solar radiation flux
- relative humidity of air
- wind speed
- rainfall variables.

These climatic variables are commonly monitored in the field, and representative values can be obtained for most regions from metrological data. The climatic variables are prescribed in the model as time-dependent variables for the computation of the surface boundary condition. A linear interpolation is used to calculate the representative climatic variables between the time-dependent values. The resolution of the prescribed data is dependent on the nature of the variables (i.e. fluctuating on an hourly or diurnal basis), the maximum simulation time step and the resolution of the original data.

The ground surface boundary is prescribed by two fluxes, one representing hydraulic surface interactions (i.e. moisture) and the other representing thermal interactions. These two fluxes are connected in two ways: (a) by the coupled heat and moisture flow formulation and (b) by the latent heat component of the energy balance equation. In order to calculate these fluxes in the model, a sequential algorithm was developed and implemented within the existing numerical code. The heat and moisture fluxes representing the ground surface boundary are calculated first at each time step. According to the surface boundary formulation, calculation of the fluxes requires ground surface information regarding temperature, relative humidity and degree of saturation. The ground properties previously listed are extracted at the beginning of flow analysis at each time step for each node located at the ground surface within the model domain. This allows the surface fluxes to be locally calculated on a node-by-node basis for the analysis. Further details can be found in Hepburn (2014).

Figure 4. Schematic diagram of a ground domain showing the ground surface boundary condition and the climatic variables required in order to calculate the ground surface boundary components

Figure 5. Daily evolution of air temperature and solar radiation recorded at the site (after Gonzalez-sosa *et al.*, 1999)

Figure 6. Daily evolution of specific air humidity and wind velocity recorded at the site (after Gonzalez-sosa *et al.*, 1999)

Model validation: evaporation at the soil atmospheric interface

The formulation developed for the ground surface boundary was tested against the results of an experimental study presented by Gonzalez-sosa *et al.* (1999). The validity of the adopted formulation for evaporation is examined against data provided by Gonzalez-sosa *et al.* (1999), where the long-term exchange of energy and water at the surface of agricultural land in southern France has been studied. As part of the experimental investigation, sensors were installed to measure the surface water exchanges and a soil investigation was carried out to obtain the soil properties at the site (Gonzalez-sosa *et al.*, 1999). A

validation model representing the thermal and hydraulic behaviour of the ground at the site for the period of monitoring (1 January 1995–7 January 1995) was developed. The climatic data, surface hydraulic components (i.e. evaporation, precipitation and run-off) and soil properties have been used. The results of hydraulic components of the ground surface boundary condition (i.e. surface run-off and evaporation) predicted by the model are compared with experimental data presented by Gonzalez-sosa *et al.* (1999).

The soil at the site has been described as a ‘typical hydromorphic bouldene with silt loam texture’ (Gonzalez-sosa *et al.*, 1999). The

Figure 7. Daily evolution of rainfall recorded at the site (after Gonzalez-sosa *et al.*, 1999)

soil properties presented by Gonzalez-sosa *et al.* (1999) were used in the simulation. The properties were presented in the form of discrete strata, the upper and lower levels. Materials were prescribed within the validation model such that they coincided with the defined strata. Beyond the depth of 1.3 m, no material data were available; therefore, the material parameters for deepest strata reported by Gonzalez-sosa *et al.* (1999) have been adopted within the remainder of the model (i.e. ground ranging from 1.3 to 10.0 m deep).

An empirical relationship describing the soil thermal conductivity was used, following Gonzalez-sosa *et al.* (1999) for the specific soil type found at the experimental site. The initial porewater pressure values at different depths were defined by Gonzalez-sosa *et al.* (1999) as a function of pressure head. van Genuchten's equation was used to describe the soil water characteristic curve (van Genuchten, 1980) by using the parameters provided by Gonzalez-sosa *et al.* (1999). The water table was reported to be at a depth of 4 m below the ground surface. Initial ground temperatures were provided at depths of 0.01, 0.05 and 0.5 m (Gonzalez-sosa *et al.*, 1999).

The initial ground temperature beyond a depth of 0.5 m was approximated using an analytical expression proposed by Hillel (1980), which provides the ground temperature profile based on soil parameters and climatic conditions, given as

$$15. \quad T(z, t) = T_a + A_0 \exp\left(-\frac{z}{d}\right) \sin\left[\frac{2\pi(t - t_0)}{365} - \frac{z}{d} - \frac{\pi}{2}\right]$$

where $T(z, t)$ is the soil temperature at time t (d) and depth z beneath the ground surface (m), T_a is the constant ground temperature ($^{\circ}\text{C}$), A_0 is the annual amplitude of the surface soil temperature ($^{\circ}\text{C}$) and t_0 is the lag time from arbitrary start date to the occurrence of the minimum soil temperature in a year (d). d is damping depth, which is calculated as

$$16. \quad d = \frac{2D_h}{\omega}$$

where D_h is thermal diffusivity (m^2/s) and ω is $2\pi/365$ (d^{-1}).

The values of A_0 and t_0 were provided by Calvet *et al.* (1999). The value of T_a is equivalent to the constant ground temperature found beyond the ground region affected by seasonal fluctuations. In the northern hemisphere, a reasonable value to assume for this is approximately 12°C (Busby *et al.*, 2011).

The climatic variables of ambient air temperature, solar radiation, specific air humidity, wind speed and rainfall presented by Gonzalez-sosa *et al.* (1999) and prescribed in the model are shown in Figures 5–7.

Figure 8. The initial and boundary conditions applied to the surface evaporation test

A two-dimensional (2D) simulation was carried out. The soil was assumed to be anisotropic in the vertical direction according to soil data provided. Climatic variables were assumed uniform across the whole site. The ground properties were assumed representative across the whole site. The selected domain extends downwards to a depth of 10 m and across to a width of 0.1 m. The model was discretised into a mesh consisting of non-structured and non-uniform linear triangular elements, so an upgrade to non-uniform 2D geometry is straightforward. A varying time-stepping algorithm was employed within the simulation. The simulation length was 5 702 400 s, coinciding with the 65-d period between 1 January and 7 March 1995.

Figure 9. Results of numerical simulations and experimental data for the total daily evaporation. Experimental data were adopted from Gonzalez-sosa *et al.* (1999)

Figure 8 presents a schematic diagram of the initial and boundary conditions for the validation exercise.

The primary aim of this model is to validate the hydraulic component of the developed surface boundary condition. The hydraulic exchange at the ground surface can be analysed knowing the controlling parameters, namely precipitation, evaporation and run-off (Deardorff, 1978). In this case, the precipitation is a measured value prescribed within the model and therefore is known to be correct. Run-off occurs only once the upper ground surface is saturated. The experimental data reported no run-off during the period investigated; therefore, the applicability of this assumption was not tested. The evaporation component of the boundary condition implemented in the model is tested by way of comparison with field data.

The simulated evaporation and the measured evaporation based on data collected at the monitoring site can be found in Figure 9. For the purpose of this comparison, the total daily evaporation (mm) for the simulated and measured data has been presented. From Figure 9, it can be seen that the simulated daily evaporation trends were generally in close agreement with those exhibited by the real data. It is noted that the simulated evaporation rates did differ from the experimental results between days 5 and 15. Based on the proximity of the deviations to the beginning of the simulation, it is believed that this period of deviation is due to the initial conditions assumed within the model. Over the 65-d simulation period, the average absolute error between the simulated and experimental data was 0.09 mm/d. The hydraulic component of the developed surface boundary condition was

analysed in terms of the predicted run-off and evaporation. At no point during the simulation did the surface reach saturation, leading to no surface run-off, concurring with the reported experimental data. The simulated evaporation showed close agreement with the measured values over the 65-d simulation period with the exception of one 10-d period.

Conclusions

A formulation for the heat and mass exchange at the soil atmospheric interface was presented. The surface boundary condition presented includes coupled thermo-hydraulic behaviour by considering a range of climatic variables and mechanisms. These include solar radiation, ambient air temperature, relative humidity, wind speed, rainfall and evaporation. The developed boundary condition has been implemented within a coupled thermal, hydraulic and mechanical numerical model by using a sequential approach.

The surface boundary condition was tested against a series of experimental data by which the validity of the hydraulic component of the surface boundary condition implemented was examined. The results of modelling the evaporation at the soil atmospheric interface were found to compare favourably with the reported values from the site. It is noted that only the results of testing the evaporation component of the model have been presented here. Further testing and validation exercises are therefore required to improve confidence in the developments.

The development and implementation of the boundary allows climatic variables to be included within future models for studying

the effects of boundary condition and climatic interactions on the performance of GSHP systems. This will enable a more detailed inspection of the climate's role in the coupled thermo-hydraulic ground behaviour in response to heat extraction by way of ground source heat systems. In particular, by using the developed boundary condition, the effects of surface material properties at the soil atmospheric interface on the performance and recharge of ground source heat systems can be investigated. The developed boundary is more sophisticated than examples found in the literature, allowing consideration of not only the climatic variables but also surface material properties. The application of this boundary within a numerical model will allow a better representation of surface materials and climatic conditions.

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