Strength of jointed rock masses

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Jointed rock masses comprise interlocking angular particles or blocks of hard brittle material separated by discontinuity surfaces which may or may not be coated with weaker materials. The strength of such rock masses depends on the strength of the intact pieces and on their freedom of movement which, in turn, depends on the number, orientation, spacing and shear strength of the discontinuities. A complete understanding of this problem presents formidable theoretical and experimental problems and, hence, simplifying assumptions are required in order to provide a reasonable basis for estimating the strength of jointed rock masses for engineering design purposes. This Paper summarizes some of the basic information upon which such simplifying assumptions can be made. A simple empirical failure criterion is presented and its application in engineering design is illustrated by means of a number of practical examples.

Des masses jointives de rochers comprennent des particules angulaires enchevêtrées ou des blocs de matière dure et cassante séparés par des surfaces discontinues enrobées ou non de matières de moindre résistance. La résistance de masses rocheuses de ce genre dépend de la résistance des morceaux intacts et de leur liberté de mouvement, qui sont fonctions elles mêmes du nombre, de l'orientation, de l'écartement et de la résistance à la rupture au cisaillement des discontinuités. La compréhension complète de ce problème présente des difficultés considérables d'aspect théorique et expérimental, de sorte que des hypothèses simplificatrices sont nécessaires pour avoir une base raisonnable sur laquelle on peut estimer la résistance des masses jointives de rochers en vue de la construction. Cet article résume quelques-unes des données de base sur lesquelles de telles hypothèses simplificatrices peuvent être faites. Un critère de rupture empirique de nature très simple est donné, son application à la construction étant illustrée au moyen d'un certain nombre d'exemples pratiques.

INTRODUCTION

The past twenty years have seen remarkable developments in the field of geotechnical engineering, particularly in the application of computers to the analysis of complex stress distribution and stability problems. There have also been important advances in the field of geotechnical equipment and instrumentation and in the

understanding of concepts such as the interaction between a concrete or steel structure and the soil foundation on which it is built or, in the case of a tunnel, the interaction between the rock mass surrounding the tunnel and the support system installed in the tunnel. Similarly, there have been significant advances in our ability to understand and to analyse the role of structural features such as joints, bedding planes and faults in controlling the stability of both surface and underground excavations.

In spite of these impressive advances, the geotechnical engineer is still faced with some areas of major uncertainty and one of these relates to the strength of jointed rock masses. This problem is summed up very well in a paper on rockfill materials by Marachi, Chan & Seed (1972) when they say 'No stability analysis, regardless of how intricate and theoretically exact it may be, can be useful for design if an incorrect estimation of the shearing strength of the construction material has been made'. These authors go on to show that, although laboratory tests on rockfill are difficult and expensive because of the size of the equipment involved, there are techniques available to permit realistic and reliable evaluation of the shear strength of typical rockfill used for dam construction.

Unfortunately, this is not true for jointed rock masses where a realistic evaluation of shear strength presents formidable theoretical and experimental problems. However, since this question is of fundamental importance in almost all major designs involving foundations, slopes or underground excavations in rock, it is essential that such strength estimates be made and that these estimates should be as reliable as possible.

In this Paper the Author has attempted to summarize what is known about the strength of jointed rock masses, to deal with some of the theoretical concepts involved and to explore their limitations and to propose some simple empirical approaches which have been found useful in solving real engineering problems. Examples of such engineering problems are given.

DEFINITION OF THE PROBLEM

Figure 1 summarizes the range of problems

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	Description	Strength characteristics	Strength testing	Theoretical considerations
Hard intact rock	Brittle, elastic and generally isotropic	Triaxial testing of core specimens in laboratory relatively simple and inexpensive and results usually reliable	Theoretical behaviour of isotropic elastic brittle rock adequately understood for most practical applications σ_1
Intact rock with single inclined discontinuity	Highly anisotropic, depending on shear strength and inclination of discontinuity	Triaxial testing of core with inclined joints difficult and expensive but results reliable. Direct shear testing of joints simple and inexpensive but results require careful interpretation	Theoretical behaviour of individual joints and of schistose rock adequately understood for most practical applications
Massive rock with a few sets of discontinuities	Anisotropic, depending on number, shear strength and continuity of discontinuities	Laboratory testing very difficult because of sample disturbance and equipment size limitations	Behaviour of jointed rock poorly understood because of complex interaction of interlocking blocks
Heavily jointed rock	Reasonably isotropic. Highly dilatant at low normal stress levels with particle breakage at high normal stress	Triaxial testing of undisturbed core samples extremely difficult due to sample disturbance and preparation problems	Behaviour of heavily jointed rock very poorly understood because of interaction of interlocking angular pieces
Compacted rockfill	Reasonably isotropic. Less dilatant and lower shear strength than in situ jointed rock but overall behaviour generally similar	Triaxial testing simple but expensive because of large equipment size required to accommodate representative samples	Behaviour of compacted rockfill reasonably well understood from soil mechanics studies on granular materials
Loose waste rock	Poor compaction and grading allow particle rotation and movement resulting in mobility of waste rock dumps	Triaxial or direct shear testing relatively simple but expensive because of large equipment size required	Behaviour of waste rock adequately understood for most applications

Fig. 1. Summary of range of rock mass characteristics

considered. In order to understand the behaviour of jointed rock masses, it is necessary to start with the components which go together to make up the system—the intact rock material and the individual discontinuity surfaces. Depending on the number, orientation and nature of the discontinuities, the intact rock pieces will translate, rotate or crush in response to stresses imposed on the rock mass. Since there are a large number of possible combinations of block shapes and sizes, it is necessary to find behavioural trends which are common to all of these combinations. The establishment of such common trends is the most important objective of this Paper.

Before embarking upon a study of the individual components and of the system as a whole, it is necessary to set down some basic definitions.

Intact rock refers to the unfractured blocks which occur between structural discontinuities in a typical rock mass. These pieces may range from a few millimetres to several metres in size and their behaviour is generally elastic and isotropic. Their failure can be classified as brittle which implies a sudden reduction in strength when a limiting stress level is exceeded. In general, viscoelastic or time-dependent behaviour such as creep is not considered to be significant unless one is dealing with evaporites such as salt or potash.

Joints are a particular type of geological discontinuity but the term tends to be used generically in rock mechanics and it usually covers all types of structural weakness with the exception of faults. Hence the term jointed rock mass may refer to an assemblage of blocks separated by joints, bedding planes, cleavage or any other type of structural weakness.

Strength, in the context of this Paper, refers to the maximum stress level which can be carried by a specimen. No attempt is made to relate this strength to the amount of strain which the specimen undergoes before failure nor is any consideration given to the post-peak behaviour or the relationship between peak and residual strength. It is recognized that these factors are important in certain engineering applications but such problems are beyond the scope of this Paper.

The presentation of rock strength data and its incorporation into a failure criterion depends on the preference of the individual and on the end use for which the criterion is intended. In dealing with slope stability problems where limit equilibrium methods of analyses are used, the most useful failure criterion is one which expresses the shear strength in terms of the effective normal stress acting across a particular weakness plane or shear zone. The presentation which is most familiar to soil mechanics engineers is the Mohr failure envelope. On the other hand, when analysing the

stability of underground excavations, the response of the rock to the principal stresses acting upon each element is of paramount interest. Consequently, a plot of triaxial test data in terms of the major principal stress at failure versus minimum principal stress or confining pressure is the most useful form of failure criterion for the underground excavation engineer. Other forms of failure criterion involving induced tensile strain, octahedral shear stress or energy considerations will not be dealt with.

Most of the discussion on failure criteria will be presented in terms of Mohr failure envelopes. With the Author's background being in underground excavation engineering the starting point for most of his studies is the triaxial test and the presentation of failure criteria in terms of principal stresses rather than shear and normal stresses. This starting point has an important bearing on the form of the empirical failure criterion presented.

STRENGTH OF THE INTACT ROCK

A vast amount of information on the strength of intact rock has been published during the past fifty years, and this was reviewed by the late Professor J. C. Jaeger in the eleventh Rankine lecture (1971).

In this context, one of the most significant steps was a suggestion by Murrell (1958) that the brittle fracture criterion proposed by Griffith (1921, 1925) could be applied to rock. Griffith postulated that, in brittle materials such as glass, fracture initiated when the tensile strength of the material is exceeded by stresses generated at the ends of microscopic flaws in the material. In rock, such flaws could be pre-existing cracks, grain boundaries or other discontinuities. Griffith's theory, summarized for rock mechanics applications by Hoek (1968), predicts a parabolic Mohr failure envelope defined by the equation

$$\tau = 2(|\sigma_t|(|\sigma_t| + \sigma'))^{1/2} \quad (1)$$

where τ is the shear stress, σ' is the effective normal stress and σ_t is the tensile strength of the material (note that tensile stresses are considered negative throughout this Paper).

Griffith's theory was originally derived for predominantly tensile stress fields. In applying this criterion to rock subjected to compressive stress conditions, it soon became obvious that the frictional strength of closed cracks has to be allowed for, and McClintock & Walsh (1962) proposed a modification to Griffith's theory to account for these frictional forces. The Mohr failure envelope for the modified Griffith theory is defined by the equation

$$\tau = 2|\sigma_t| + \sigma' \tan \phi' \quad (2)$$

where ϕ' is the angle of friction on the crack

Fig. 2. Mohr circles for failure of specimens of quartzite tested by Hoek (1965). Envelopes included in the figure are calculated by means of the original and modified Griffith theories of brittle fracture initiation

surfaces. (Note, this equation is only valid for $\sigma' > 0$.)

Detailed studies of crack initiation and propagation by Hoek & Bieniawski (1965) and Hoek (1968) showed that the original and modified Griffith theories are adequate for the prediction of fracture initiation in rocks but that they fail to describe fracture propagation and failure of a sample. Fig. 2 gives a set of Mohr circles for failure of specimens of quartzite tested triaxially (Hoek, 1965). Included in this figure are Mohr envelopes calculated by means of equations (1) and (2) for $\sigma_t = 18.6$ MPa and $\phi' = 50$ degrees. Neither of these curves can be considered acceptable envelopes to the Mohr circles representing failure of the quartzite under compressive stress conditions. In spite of the inadequacy of the original and modified Griffith theories in predicting the failure of intact rock specimens, a study of the mechanics of fracture initiation and of the shape of the Mohr envelopes predicted by these theories was a useful starting point in deriving the empirical failure criterion.

Jaeger (1971), in discussing failure criteria for rock, comments that 'Griffith theory has proved extraordinarily useful as a mathematical model for studying the effect of cracks on rock, but it is essentially only a mathematical model; on the microscopic scale rocks consist of an aggregate of anisotropic crystals of different mechanical properties and it is these and their grain boundaries which determine the microscopic behaviour'.

Recognition of the difficulty involved in developing a mathematical model which adequately predicts fracture propagation and

failure in rock led a number of authors to propose empirical relationships between principal stresses or between shear and normal stresses at failure. Murrell (1965), Hoek (1968), Hobbs (1970) and Bieniawski (1974a) all proposed different forms of empirical criteria. The failure criterion on which the remainder of this Paper is based was presented by Hoek & Brown (1980a, 1980b) and resulted from their efforts to produce an acceptable failure criterion for the design of underground excavations in rock.

AN EMPIRICAL FAILURE CRITERION FOR ROCK

In developing their empirical failure criterion, Hoek & Brown (1980a) attempted to satisfy the following conditions

- The failure criterion should give good agreement with experimentally determined rock strength values.
- The failure criterion should be expressed by mathematically simple equations based, to the maximum extent possible, upon dimensionless parameters.
- The failure criterion should offer the possibility of extension to deal with anisotropic failure and the failure of jointed rock masses.

The studies on fracture initiation and propagation suggested that the parabolic Mohr envelope predicted by the original Griffith theory adequately describes both fracture initiation and failure of brittle materials under conditions where the effective normal stress acting across a pre-existing crack is tensile (negative). This is because fracture propagation follows very quickly upon

Fig. 3. Summary of equations associated with the non-linear failure criterion proposed by Hoek & Brown (1980b)

fracture initiation under tensile stress conditions, and hence fracture initiation and failure of the specimen are practically indistinguishable.

Figure 2 shows that, when the effective normal stress is compressive (positive), the envelope to the Mohr circles tends to be curvilinear, but not to the extent predicted by the original Griffith theory.

Based upon these observations, Hoek & Brown (1980a) experimented with a number of distorted parabolic curves to find one which gave good coincidence with the original Griffith theory for tensile effective normal stresses, and which fitted the observed failure conditions for brittle rocks subjected to compressive stress conditions.

The process used by Hoek & Brown in deriving their empirical failure criterion was one of pure trial and error. Apart from the conceptual starting point provided by Griffith theory, there is no fundamental relationship between the empirical constants included in the criterion and any physical characteristics of the rock. The justification for choosing this particular criterion over the numerous alternatives lies in the adequacy of its predictions of observed rock fracture behaviour, and the convenience of its application to a range of typical engineering problems.

The Author's background in designing underground excavations in rock resulted in the decision to present the failure criterion in terms of the major and minor principal stresses at failure. The empirical equation defining the relationship between these stresses is

$$\sigma_1' = \sigma_3' + (m\sigma_c\sigma_3' + s\sigma_c^2)^{1/2} \quad (3)$$

where σ_1' is the major principal effective stress at failure, σ_3' is the minor principal effective stress or, in the case of a triaxial test, the confining pressure, σ_c is the uniaxial compressive strength of the intact rock material from which the rock mass is made up, and m and s are empirical constants.

The constant m always has a finite positive value which ranges from about 0.001 for highly disturbed rock masses, to about 25 for hard intact rock. The value of the constant s ranges from 0 for jointed masses, to 1 for intact rock material.

Substitution of $\sigma_3' = 0$ into equation (3) gives the unconfined compressive strength of a rock mass as

$$\sigma_1' = \sigma_c = (s\sigma_c^2)^{1/2} \quad (4)$$

Similarly, substitution of $\sigma_1' = 0$ in equation (3), and solution of the resulting quadratic equation for σ_3' , gives the uniaxial tensile strength of a rock mass as

$$\sigma_3' = \sigma_t = \frac{1}{2}\sigma_c(m - (m^2 + 4s)^{1/2}) \quad (5)$$

The physical significance of equations (3)–(5) is illustrated in the plot of σ_1' against σ_3' given in Fig. 3.

While equation (3) is very useful in designing underground excavations, where the response of individual rock elements to in situ and induced stresses is important, it is of limited value in designing rock slopes where the shear strength of a failure surface under specified effective normal stress conditions is required. The Mohr failure envelope corresponding to the empirical failure criterion defined by equation (3) was derived by Dr J. Bray of Imperial College and is given by

$$\tau = (\cot \phi_i' - \cos \phi_i') \frac{m\sigma_c}{8} \quad (6)$$

where τ is the shear stress at failure, ϕ_i' is the instantaneous friction angle at the given values of τ and σ' —i.e. the inclination of the tangent to the Mohr failure envelope at the point (σ', τ) as shown in Fig. 3.

The value of the instantaneous friction angle ϕ_i' is given by

$$\phi_i' = \text{Arctan}(4h \cos^2(30 + \frac{1}{3} \text{Arcsin } h^{-3/2}) - 1)^{-1/2} \quad (7)$$

where

$$h = 1 + \frac{16(m\sigma' + s\sigma_c)}{3m^2\sigma_c}$$

and σ' is the effective normal stress.

The instantaneous cohesive strength c_i' , shown in Fig. 3, is given by

$$c_i' = \tau - \sigma' \tan \phi_i' \quad (8)$$

From the Mohr circle construction given in Fig. 3, the failure plane inclination β is given by

$$\beta = 45 - \frac{1}{2}\phi_i' \quad (9)$$

An alternative expression for the failure plane inclination, in terms of the principal stresses σ_1' and σ_3' , was derived by Hoek & Brown (1980a):

$$\beta = \frac{1}{2} \text{Arcsin} \frac{\tau_m}{\tau_m + m\sigma_c/8} (1 + m\sigma_c/4\tau_m)^{1/2} \quad (10)$$

where $\tau_m = \frac{1}{2}(\sigma_1' - \sigma_3')$.

CHARACTERISTICS OF EMPIRICAL CRITERION

The empirical failure criterion presented in the preceding section contains three constants; m , s and σ_c . The significance of each of these will be discussed in turn later.

Constants m and s are both dimensionless and are very approximately analogous to the angle of friction, ϕ' , and the cohesive strength, c' , of the conventional Mohr–Coulomb failure criterion.

Figure 4 illustrates the influence of different values of the constant m on the Mohr failure envelope for intact rock. In plotting these curves,

Fig. 4. Influence of the value of the constant m on the shape of the Mohr failure envelope and on the instantaneous friction angle at different effective normal stress levels

the values of both s and σ_c are assumed equal to unity.

Large values of m , in the order of 15–25, give steeply inclined Mohr envelopes and high instantaneous friction angles at low effective normal stress levels. These large m values tend to be associated with brittle igneous and metamorphic rocks such as andesites, gneisses and granites. Lower m values, in the order of 3–7, give lower instantaneous friction angles and tend to be associated with more ductile carbonate rocks such as limestone and dolomite.

The influence of the value of the constant s on the shape of the Mohr failure envelope and on the

instantaneous friction angle at different effective normal stress levels is illustrated in Fig. 5. The maximum value of s is 1, and this applies to intact rock specimens which have a finite tensile strength (defined by equation (5)). The minimum value of s is zero, and this applies to heavily jointed or broken rock in which the tensile strength has been reduced to zero and where the rock mass has zero cohesive strength when the effective normal stress is zero.

The third constant, σ_c , the uniaxial compressive strength of the intact rock material, has the dimensions of stress. This constant was chosen after very careful consideration of available rock

strength data. The unconfined compressive strength is probably the most widely quoted constant in rock mechanics, and it is likely that an estimate of this strength will be available in cases where no other rock strength data are available. Consequently, it was decided that the uniaxial compressive strength σ_c would be adopted as the basic unit of measurement in the empirical failure criterion.

The failure criterion defined by equation (3) can be made entirely dimensionless by dividing both sides by the uniaxial compressive strength

$$\sigma_1'/\sigma_c = \sigma_3'/\sigma_c + (m\sigma_3'/\sigma_c + s)^{1/2} \quad (11)$$

This formulation, which can also be achieved by simply putting $\sigma_c = 1$ in equation (3), is very useful when comparing the shape of Mohr failure envelopes for different rock materials.

A procedure for the statistical determination of the values of the constants m , s and σ_c from

Fig. 5. Influence of the value of the constant s on the shape of the Mohr failure envelope and on the instantaneous friction angle at different effective normal stress levels

experimental data is given in Appendix 1.

TRIAXIAL DATA FOR INTACT ROCK

Hoek & Brown (1980a) analysed published data from several hundred triaxial tests on intact rock specimens and found some useful trends. These trends will be discussed in relationship to the two sets of data plotted as Mohr failure circles in Fig. 6. The sources of the triaxial data plotted in Fig. 6 are given in Table 1.

Figure 6(a) gives Mohr failure envelopes for five different granites from the USA and UK. Tests on these granites were carried out in five different laboratories using different triaxial equipment. In spite of these differences, the failure characteristics of these granites follow a remarkably consistent pattern, and the Mohr failure envelope predicted by equations (6) and (7) for $\sigma_c = 1$, $m = 29.2$ and $s = 1$ fits all of these Mohr circles very well. Table 1 shows that a correlation coefficient of 0.99 was obtained by statistically fitting the empirical failure criterion defined by equation (3) to all of the granite strength data.

The term granite defines a group of igneous rocks having very similar mineral composition, grain size and angularity, and hence the failure characteristics exhibited by these rocks are very similar, irrespective of the source of the granite. The trend illustrated in Fig. 6(a) has very important practical implications, since it suggests that it should be possible, given a description of the rock and an estimate of its uniaxial compressive strength, to predict its Mohr failure envelope with a relatively high degree of confidence. This is particularly important in early conceptual or feasibility studies where the amount of reliable laboratory data is very limited.

In contrast to the trends illustrated in Fig. 6(a) for granite, the plot given in Fig. 6(b) for limestone is less convincing. In this case, eleven different limestones, tested in three different laboratories, have been included in the plot. Table 1 shows that the values of the constant m , derived from statistical analyses of the test data, vary from 3.2 to 14.1, and that the correlation coefficient for the complete data set is only 0.68.

The scatter of the data included in Fig. 6(b) is attributed to the fact that the generic term limestone applies to a range of carbonate rocks formed by deposition of a variety of organic and inorganic materials. Consequently, mineral composition, grain size and shape, and the nature of cementing materials between the grains, will vary from one limestone to another.

Comparison of the two plots given in Fig. 6 suggests that the empirical failure criterion presented here gives a useful indication of the general trend of the Mohr failure envelope for

Table 1. Sources of data included in Fig. 6*

Rock type	Location	Reference	Number tested	Uniaxial compressive strength		Each sample		Rock type	
				lb/in ²	MPa	m	r ² †	m	r ² †
Granite	Westerley, USA	Heard <i>et al.</i> (1974)	17	31 040	214.0	26.7	1.00		
	Westerley, USA	Wawersik & Brace (1971)	7	43 310	298.6	27.0	1.00		
	Westerley, USA	Brace (1964)	7	49 820	343.5	28.3	0.98		
	Westerley, USA	Mogi (1967)	6	32 440	223.7	32.8	0.99		
	Stone Mountain, USA	Schwartz (1964)	14	16 850	116.2	28.9	0.93	29.2	0.99
	Blackingstone, UK	Franklin & Hoek (1970)	48	30 410	209.7	20.8	0.91		
	Mount Sorrel, UK	Misra (1972)	5	39 910	275.2	26.5	0.99		
	Carnmarth, Redruth, UK	Misra (1972)	5	23 540	162.3	27.7	0.99		
	Portland, UK	Franklin & Hoek (1970)	30	13 300	91.7	7.5	0.72		
	Indiana, USA	Schwartz (1964)	6	7090	48.9	3.2	0.95		
Limestone	Bath, UK	Misra (1972)	7	6830	47.1	5.5	0.97		
	Grindling Stubbs, UK	Misra (1972)	6	19 450	134.1	8.8	0.97		
	Kirbymoorside, UK	Misra (1972)	5	23 830	164.3	12.3	0.98		
	Blackwell, UK	Misra (1972)	5	29 211	201.4	10.0	0.92	5.4	0.68
	Foster Yeoman, UK	Misra (1972)	5	24 265	167.3	14.1	0.95		
	Giggleswick, UK	Misra (1972)	5	22 423	154.6	8.8	0.97		
	Kelmac, UK	Misra (1972)	5	16 897	116.5	7.3	1.00		
	Threshfield, UK	Misra (1972)	5	21 423	147.7	6.9	0.98		
	Swinden Cracoe, UK	Misra (1972)	5	16 027	110.5	8.4	0.96		

* Material constant $s = 1$ for intact rock.† r^2 is coefficient of determination or correlation coefficient.

(a)

(b)

Fig. 6. Mohr failure circles for published triaxial test data for intact samples of (a) granite and (b) limestone

different rock types. The accuracy of each prediction will depend on the adequacy of the description of the particular rock under consideration. In comparing the granites and limestones included in Fig. 6, there would obviously be a higher priority in carrying out confirmatory laboratory tests on the limestone than on the granite.

Hoek & Brown (1980a) found that there were definite trends which emerged from the statistical fitting of their empirical failure criterion (equation (3)) to published triaxial data. For intact rock (for which $s = 1$), these trends are characterized by the value of the constant m which, as illustrated in Fig. 4, defines the shape of the Mohr failure envelope. The trends suggested by Hoek & Brown (1980a) are

- (a) Carbonate rocks with well developed crystal cleavage (dolomite, limestone and marble); $m = 7$
- (b) Lithified argillaceous rocks [mudstone, shale and slate (normal to cleavage)]; $m = 10$
- (c) Arenaceous rocks with strong crystals and poorly developed crystal cleavage (sandstone and quartzite); $m = 15$
- (d) Fine grained polyminerallic igneous crystalline rocks (andesite, dolerite, diabase and rhyolite); $m = 17$
- (e) Course grained polyminerallic igneous and metamorphic rocks (amphibolite, gabbro, gneiss, granite, norite and granodiorite); $m = 25$

These trends will be utilized later when the

estimation of the strength of the jointed rock masses is discussed.

The fitting of the empirical failure criterion defined by equation (3) to a particular set of triaxial data is illustrated in Fig. 7. The Mohr circles plotted were obtained by Bishop & Garga (1969) from a series of carefully performed triaxial tests on undisturbed samples of London clay (Bishop, Webb & Lewin, 1965). The Mohr envelope plotted in Fig. 7 was determined from a statistical analysis of Bishop & Garga's data (using the technique described in Appendix 1), and the values of the constants are $\sigma_c = 211.8 \text{ kPa}$, $m = 6.475$ and $s = 1$. The correlation coefficient for the fit of the empirical criterion to the experimental data is 0.98.

This example was chosen for its curiosity value rather than its practical significance, and because of the strong association between the British Geotechnical Society and previous Rankine lecturers and London clay. The example does serve to illustrate the importance of limiting the use of the empirical failure criterion to a low effective normal stress range. Tests on London clay at higher effective normal stress levels by Bishop *et al.* (1965) gave approximately linear Mohr failure envelopes with friction angles of about 11° .

As a rough rule of thumb, when analysing intact rock behaviour, the Author limits the use of the empirical failure criterion to a maximum effective normal stress level equal to the unconfined compressive strength of the material. This question is examined later in a discussion on brittle-ductile transition in intact rock.

Fig. 7. Mohr failure envelope for drained triaxial tests at very low normal stress levels carried out by Bishop & Garga (1969) on undisturbed samples of London clay

Table 2. Observed and predicted failure plane inclination for Tennessee marble (Wawersik, 1968)

Confining pressure: MPa	Axial strength: MPa	Observed fracture angle	Predicted fracture angle
0	134.48	18.0	26.61
3.45	143.45	23.4	27.0
6.90	160.00	24.8	27.7
13.79	186.21	31.7	28.7
20.69	201.38	35.1	29.1
27.59	220.00	36.3	29.7
34.48	251.03	37.8	30.6
48.28	286.21	38.8	31.4

ASSUMPTIONS INCLUDED IN EMPIRICAL FAILURE CRITERION

A number of simplifying assumptions have been made in deriving the empirical failure criterion, and it is necessary to discuss these assumptions before extending the criterion to deal with jointed rock masses.

Effective stress

Throughout this discussion, it is assumed that the empirical failure criterion is valid for effective stress conditions. In other words, the effective stress σ' used in equations (7) and (8) is obtained from $\sigma' = \sigma - u$, where σ is the applied normal stress and u is the pore or joint water pressure in the rock. In spite of some controversy on this subject, discussed by Jaeger & Cook (1969), Brace & Martin (1968) demonstrate that the effective stress concept appears to be valid in intact rocks of extremely low permeability, provided that loading rates are sufficiently low to permit pore pressures to equalize. For porous rocks such as sandstone, normal laboratory loading rates will generally satisfy effective stress conditions (Handin, Hager, Friedman & Feather, 1963) and there is no reason to suppose that they will not apply in the case of jointed rocks.

Influence of pore fluid on strength

In addition to the influence of pore pressure on strength, it is generally accepted that the pore fluid itself can have a significant influence on rock strength. For example, Colback & Wiid (1965) and Broch (1974) showed that the unconfined compressive strength of quartzitic shale, quartz-diorite, gabbro and gneiss can be reduced by as much as two by saturation in water as compared with oven dried specimens. Analyses of their results suggest that this reduction takes place in the unconfined compressive strength σ_c and not in the constant m of the empirical failure criterion.

It is important, in testing rock materials or in comparing data from rock strength tests, that the

moisture content of all specimens be kept within a narrow range. In the Author's own experience in testing samples of shale which had been left standing on the laboratory shelf for varying periods of time, the very large amount of scatter in strength data was almost eliminated by storing the specimens in a concrete curing room to bring them close to saturation before testing. Obviously, in testing rocks for a particular practical application, the specimens should be tested as close to in situ moisture content as possible.

Influence of loading rate

With the exception of effective stress tests on very low porosity materials (e.g. Brace & Martin, 1968), or tests on viscoelastic materials such as salt or potash, it is generally assumed that the influence of loading rate is insignificant when dealing with rock. While this may be an oversimplification, the Author believes that it is sufficiently accurate for most practical applications.

Influence of specimen size

Hoek & Brown (1980a) have analysed the influence of specimen size on the results of strength tests on the intact rock samples. They found that the influence of specimen size can be approximated by the relationship

$$\sigma_c = \sigma_{c50}(50/d)^{0.18} \quad (12)$$

where σ_c is the unconfined compressive strength, d is the diameter of the specimen in millimetres and σ_{c50} is the unconfined compressive strength of a 50 mm diameter specimen of the same material.

In the case of jointed rocks, the influence of size is controlled by the relationship between the spacing of joints and the size of the sample. This problem is dealt with later in the discussion on jointed rock masses.

Influence of intermediate principal stress

In deriving the empirical failure criterion presented here, Hoek & Brown (1980a) assumed

Fig. 8. Plot of Mohr failure circles for Tennessee marble tested by Wawersik (1968) giving comparison between predicted and observed failure plane inclinations

that the failure process is controlled by the major and minor principal stresses σ_1' and σ_3' , and that the intermediate principal stress σ_2' has no significant influence upon this process. This is almost certainly an over-simplification, but there appears to be sufficient evidence (reviewed by Jaeger & Cook, 1969) to suggest that the influence of the intermediate principal stress can be ignored without introducing unacceptably large errors.

Failure surface inclination

The inclination of an induced failure plane in an intact rock specimen is given by equations (9) or (10). This inclination is measured from the direction of the maximum principal stress σ_1' , as illustrated in Fig. 3.

The results of a series of triaxial tests by Wawersik (1968) on Tennessee marble are listed in Table 2, and plotted as Mohr circles in Fig. 8. Also listed in Table 2 and plotted in Fig. 8, are observed failure plane inclinations.

A statistical analysis of the triaxial test data gives the following constants: $\sigma_c = 132$ MPa, $m = 6.08$, $s = 1$, with a correlation coefficient $r^2 = 0.99$. The Mohr envelope defined by these constants is plotted as a dashed curve in Fig. 8.

The predicted fracture angles listed in Table 2 have been calculated for $\sigma_c = 132$ MPa and $m = 6.08$ by means of equation (10), and there are significant differences between observed and predicted fracture angles.

However, a Mohr envelope fitted through the shear stress (τ) and effective normal stress (σ')

points defined by construction (using the Mohr circles), gives a value of $m = 5.55$ for $\sigma_c = 132$ MPa and $s = 1$. The resulting Mohr envelope, plotted as a full line in Fig. 8, is not significantly different from the Mohr envelope determined by analysis of the principal stresses.

These findings are consistent with the Author's own experience in rock testing. The fracture angle is usually very difficult to define, and is sometimes obscured altogether. This is because, as discussed earlier, the fracture process is complicated and does not always follow a clearly defined path. When the failure plane is visible, the inclination of this plane cannot be determined to better than $\pm 5^\circ$. In contrast, the failure stresses determined from a carefully conducted set of triaxial tests are usually very clearly grouped, and the pattern of Mohr circles plotted in Fig. 8 is not unusual in intact rock testing.

To conclude, the failure plane inclinations predicted by equations (9) or (10) should be regarded as approximate only, and that, in many rocks, no clearly defined failure surfaces will be visible.

Brittle-ductile transition

The results of a series of triaxial tests carried out by Schwartz (1964) on intact specimens of Indiana limestone are plotted in Fig. 9. A transition from brittle to ductile behaviour appears to occur at a principal stress ratio of approximately $\sigma_1'/\sigma_3' = 4.3$.

A study of the failure characteristics of a number

Fig. 9. Results of triaxial tests on Indiana limestone carried out by Schwartz (1964) illustrating brittle-ductile transition

Fig. 10. Results of direct shear tests on moderately weathered greywacke, tested by Martin & Miller (1974), compared with empirical failure envelopes

of rocks by Mogi (1966) led him to conclude that the brittle-ductile transition for most rocks occurs at an average principal stress ratio $\sigma_1'/\sigma_3' = 3.4$.

Examination of the results plotted in Fig. 9, and of similar results plotted by Mogi, shows that there is room for a wide variety of interpretations of the critical principal stress ratio, depending on the curve fitting procedure employed and the choice of the actual brittle-ductile transition point. The range of possible values of σ_1'/σ_3' appears to lie between 3 and 5.

A rough rule of thumb used by the Author is that the confining pressure σ' must always be less than the unconfined compressive strength σ_c of the material for the behaviour to be considered brittle. In the case of materials characterized by very low values of the constant m , such as the Indian limestone considered in Fig. 9 ($m = 3.2$), the value of $\sigma' = \sigma_c$ may fall beyond the brittle-ductile transition. However, for most rocks encountered in practical engineering applications, this rule of thumb appears to be adequate.

SHEAR STRENGTH OF DISCONTINUITIES

The shear strength of discontinuities in rock has been extensively discussed by a number of authors such as Patton (1966), Goodman (1970), Ladanyi & Archambault (1970), Barton (1971, 1973, 1974), Barton & Choubey (1977) and Richards & Cowland (1982). These discussions have been summarized by Hoek & Bray (1981).

For practical field applications involving the estimation of the shear strength of rough discontinuity surfaces in rock, the Author recommends the following empirical relationship

between shear strength (τ) and effective normal stress (σ') proposed by Barton (1971, 1973).

$$\tau = \sigma' \tan(\phi_b' + \text{JRC} \log_{10}(\text{JCS}/\sigma')) \quad (13)$$

where ϕ_b' is the 'basic' friction angle of smooth planar discontinuities in the rock under consideration, JRC is a joint roughness coefficient which ranges from 5 for smooth surfaces, to 20 for rough undulating surfaces, and JCS is the joint wall compressive strength which, for clean unweathered discontinuities, equals the uniaxial compressive strength of the intact rock material.

While Barton's equation is very useful for field applications, it is not the only one which can be used for fitting to laboratory shear test data, e.g. Krstanovic (1967), Martin & Miller (1974) and Hencher & Richards (1982).

Figure 10 gives a plot of direct shear strength data obtained by Martin & Miller (1974) from tests on 150 mm by 150 mm joint surfaces in moderately weathered greywacke (grade 3, test sample number 7). Barton's empirical criterion (equation (13)) was fitted by trial and error, and the dashed curve plotted in Fig. 10 is defined by $\phi_b' = 20^\circ$, JRC = 17 and JCS = 20 MPa.

Also included in Fig. 10 is a Mohr envelope defined by equations (6) and (7) for $\sigma_c = 20$ MPa, $m = 0.58$ and $s = 0$ (determined by the method described in Appendix 1). This curve is just as good a fit to the experimental data as Barton's curve.

A number of analyses, such as that presented in Fig. 10, have convinced the Author that equations (6) and (7) provide a reasonably accurate prediction of the shear strength of rough discontinuities in rock under a wide range of effective

Fig. 11. (a) Configuration of triaxial test specimen containing a pre-existing discontinuity; (b) strength of specimen predicted by means of equations (14) and (3)

normal stress conditions. This fact is useful in the study of schistose and jointed rock mass strength which follows.

STRENGTH OF SCHISTOSE ROCK

In the earlier part of this Paper, the discussion on the strength of intact rock was based on the assumption that the rock was isotropic, i.e. its strength was the same in all directions. A common problem encountered in rock mechanics involves the determination of the strength of schistose or layered rocks such as slates or shales.

If it is assumed that the shear strength of the discontinuity surfaces in such rocks is defined by an instantaneous friction angle ϕ_i' and an instantaneous cohesion c_i' (see Fig. 3), then the axial strength σ_1' of a triaxial specimen containing inclined discontinuities is given by the following equation (see Jaeger & Cook, 1969, pp. 65–68)

$$\sigma_1' = \sigma_3' + \frac{2(c_i' + \sigma_3' \tan \phi_i')}{(1 - \tan \phi_i' \tan \beta) \sin 2\beta} \quad (14)$$

where σ_3' is the minimum principal stress or confining pressure, and β is the inclination of the discontinuity surfaces to the direction of the major principal stress σ_1 as shown in Fig. 11(a).

Equation (14) can only be solved for values of β within about 25° of the friction angle ϕ' . Very small values of β will give very high values for σ_1' , while values of β close to 90° will give negative (and

hence meaningless) values for σ_1' . The physical significance of these results is that slip on the discontinuity surfaces is not possible, and failure will occur through the intact material as predicted by equation (3). A typical plot of the axial strength σ_1' against the angle β is given in Fig. 11(b).

If it is assumed that the shear strength of the discontinuity surfaces can be defined by equations (6) and (7), as discussed previously, then in order to determine the values of ϕ_i' and c_i' for substitution into equation (14), the effective normal stress σ' acting across the discontinuity must be known. This is found from

$$\sigma' = \frac{1}{2}(\sigma_1' + \sigma_3') - \frac{1}{2}(\sigma_1' - \sigma_3') \cos 2\beta \quad (15)$$

However, since σ_1' is the strength to be determined, the following iterative process can be used

- Calculate the strength σ_{1i}' of the intact material by means of equation (3), using the appropriate values of σ_c , m and s .
- Determine values of m_i and s_i for the joint (discontinuity) surfaces from direct shear or triaxial test data. The value of σ_c , the unconfined compressive strength, is the same for the intact material and the discontinuity surfaces in this analysis.
- Use the value of σ_{1i}' , calculated in (a), to obtain the first estimate of the effective normal stress σ' from equation (15).

Fig. 12. Triaxial test results for slate with different failure plane inclinations, obtained by McLamore & Gray (1967), compared with strength predictions from equations (3) and (14)

- (d) Calculate τ , ϕ_i' and c_i' from equations (6)–(8), using the value of m_j and s_j from (b), and the value of σ' from (c).
- (e) Calculate the axial strength σ_{1j}' from equation (14).
- (f) If σ_{1j}' is negative or greater than σ_{1i}' , the failure of the intact material occurs in preference to, slip on the discontinuity, and the strength of the specimen is defined by equation (3).
- (g) If σ_{1j}' is less than σ_{1i}' then failure occurs as a result of slip on the discontinuity. In this case, return to (c) and use the axial strength calculated in (e) to calculate a new value for the effective normal stress σ' .
- (h) Continue this iteration until the difference between successive values of σ_{1j}' in (e) is less than 1%. Only three or four iterations are required to achieve this level of accuracy.

Examples of the analysis described above are given in Figs 12 and 13.

The results of triaxial tests on slate tested by McLamore & Gray (1967) for a range of confining pressures and cleavage orientations are plotted in Fig. 12. The solid curves have been calculated, using the method outlined above, for

$\sigma_c = 217$ MPa (unconfined strength of intact rock), $m = 5.25$ and $s = 1.00$ (constants for intact rock), and $m_j = 1.66$ and $s_j = 0.006$ (constants for discontinuity surfaces).

The values of the constants m_j and s_j for the discontinuity surfaces were determined by statistical analysis of the minimum axial strength values, using the procedure for broken rock described in Appendix 1.

A similar analysis is presented in Fig. 13, which gives results from triaxial tests on sandstone by Horino & Ellikson (1970). In this case the discontinuity surfaces were created by intentionally fracturing intact sandstone in order to obtain very rough fresh surfaces. The constants used in plotting the solid curves in Fig. 13 were $\sigma_c = 177.7$ MPa (intact rock strength), $m = 22.87$ and $s = 1.00$ (constants for intact rock), and $m_j = 4.07$ and $s_j = 0$ (constants for induced fracture planes).

The rougher failure surfaces in the sandstone, as compared to the slate (compare values of m_j), give more sudden changes in axial strength with discontinuity inclination. In both these cases, and in a number of other examples analysed, the agreement between measured and predicted

Fig. 13. Triaxial test results for fractured sandstone, tested by Horino & Ellikson (1970), compared with predicted anisotropic strength

strengths is adequate for most practical design purposes.

An example of the application of the analysis of anisotropic failure, is given later. This example involves the determination of the stress distribution and potential failure zones in highly stressed schistose rock surrounding a tunnel.

FAILURE OF JOINTED ROCK MASSES

Having studied the strength of intact rock and of discontinuities in rock, the next logical step is to attempt to predict the behaviour of a jointed rock mass containing several sets of discontinuities. The simplest approach to this problem is to superimpose a number of analyses for individual discontinuity sets, such as those presented in Figs 12 and 13, in the hope that the overall behaviour pattern obtained would be representative of the behaviour of an actual jointed rock mass.

Verification of the results of such predictions presents very complex experimental problems, and many research workers have resorted to the use of physical models in an attempt to minimize these experimental difficulties. Lama & Vutukuri (1978) have summarized the results of model studies

carried out by John (1962), Muller & Pacher (1965), Lajtai (1967), Einstein, Nelson, Bruhn & Hirschfield (1969), Ladanyi & Archambault (1970, 1972), Brown (1970), Brown & Trollope (1970), Walker (1971) and others. One of these studies, published by Ladanyi & Archambault (1972), will be considered here.

Ladanyi & Archambault constructed models from rods, with a square cross-section of 12.7 mm by 12.7 mm and a length of 63.5 mm, which had been sawn from commercial compressed concrete bricks. The Mohr failure envelopes for the intact concrete material and for the sawn 'joints' in the model are given in Fig. 14. These curves were derived by statistical analysis of raw test data supplied by Professor Ladanyi.

One of the model configurations used by Ladanyi & Archambault (1972) is illustrated in Fig. 15. Failure of the model in the direction of the 'cross joints' (inclined at an angle α to the major principal stress direction) involves fracture of intact material as well as sliding on the joints. A crude first approximation of the model strength in the α direction is obtained by simple averaging of the Mohr failure envelopes for the intact material

Fig. 14. Mohr failure envelopes for brickwall model tested by Ladanyi & Archambault (1972)

and the through-going joints. The resulting strength estimate is plotted as a Mohr envelope in Fig. 14.

The predicted strength behaviour of Ladanyi & Archambault's 'brickwall' model, for different joint orientations and lateral stress levels, is given in Fig. 16(a). These curves have been calculated, from the strength values given in Fig. 14, by means of equations (14), (15) and (3). The actual strength values measured by Ladanyi & Archambault are plotted in Fig. 16(b). Comparison between these two figures leads to the following conclusions

- There is an overall similarity between predicted and observed strength behaviour which suggests that the approach adopted in deriving the curves plotted in Fig. 16(a) is not entirely inappropriate.
- The observed strengths are generally lower than the predicted strengths. The intact material strength is not achieved, even at the most favourable joint orientations. The sharply defined transitions between different failure modes, predicted in Fig. 16(a), are smoothed out by rotation and crushing of individual blocks. This behaviour is illustrated in the series of photographs reproduced in Fig. 17. In particular, the formation of 'kink bands', as illustrated in Fig. 17(c), imparts a great deal of mobility to the model and results in a

Fig. 15. Configuration of brickwall model tested by Ladanyi & Archambault (1972)

Fig. 16. Comparison between (a) predicted and (b) observed strength of brickwall model tested by Ladanyi & Archambault (1972)

Fig. 17. (a) Shear plane failure; (b) shear zone failure; and (c) kink band failure observed in concrete brick models tested by Ladanyi & Archambault (1972). Photograph reproduced with the permission of Professor B. Ladanyi

Fig. 18. Comparison between the strengths of intact and granulated Carrara marble tested by Gerogiannopoulos (1979)

Fig. 19. Mohr failure envelopes for (a) intact and (b) heavily jointed Panguna andesite from Bougainville, Papua New Guinea (see Table 3 for description of materials)

Table 3. Details of materials and test procedures for Panguna andesite

Material	Tested by	Sample diameter: mm	Material constants
Intact Panguna andesite	Jaeger (1970) Golder Associates	25 50	$\sigma_c = 265.4 \text{ MPa}$ $m = 18.9$ $s = 1$ Correlation coefficient 0.85
Undisturbed core samples of heavily jointed andesite obtained by triple-tube diamond core drilling in exploration adit	Jaeger (1970)	152	$m = 0.277$ $s = 0.0002$ Correlation coefficient 0.99
Recompacted sample of heavily jointed andesite collected from mine benches (equivalent to compacted fresh rock-fill)	Bougainville Copper	152	$m = 0.116$ $s = 0$
Fresh to slightly weathered andesite, lightly recompacted	Snowy Mountains Engineering Corporation	570	$m = 0.040$ $s = 0$
Moderately weathered andesite, lightly recompacted	Snowy Mountains Engineering Corporation	570	$m = 0.030$ $s = 0$
Completely weathered andesite (equivalent to poor quality waste rock)	Snowy Mountains Engineering Corporation	570	$m = 0.012$ $s = 0$

significant strength reduction in the zone defined by $15 > \alpha > 45$, as shown in Fig. 16(b).

- (c) Intuitive reasoning suggests that the degree of interlocking of the model blocks is of major significance in the behaviour of the model since this will control the freedom of the blocks to rotate. In other words, the freedom of a rock mass to dilate will depend on the interlocking of individual pieces of rock which, in turn, will depend on the particle shape and degree of disturbance to which the mass has been subjected. This reasoning is supported by experience in strength determination of rockfill where particle strength and shape, particle size distribution and degree of compaction are all important factors in the overall strength behaviour.
- (d) Extension of the principle of strength prediction used in deriving the curves presented in Fig. 16(a) to rock masses, containing three, four or five sets of discontinuities, suggests that the behaviour of such rock masses would approximate to that of a homogeneous isotropic system. In practical terms, this means that, for most rock masses containing a number of joint sets with similar strength characteristics, the overall strength behaviour will be similar to that of a very tightly interlocking rockfill.

The importance of the degree of interlocking between particles in a homogeneous rock mass can be illustrated by considering the results of an

ingenious experiment carried out by Rosengren & Jaeger (1968), and repeated by Gerogiannopoulos (1979). By heating specimens of coarse grained marble to about 600°C , the cementing material between grains is fractured by differential thermal expansion of the grains themselves. The material produced by this process is a very low porosity assemblage of extremely tightly interlocking but independent grains. This 'granulated' marble was tested by Rosengren & Jaeger (1968) and Gerogiannopoulos (1979) in an attempt to simulate the behaviour of an undisturbed jointed rock mass.

The results obtained by Gerogiannopoulos from triaxial tests on both intact and granulated Carrara marble are plotted in Fig. 18. In order to avoid confusion, Mohr failure circles for the granulated material only are included in this figure. However, statistical analyses of the data sets for both intact and granulated materials to obtain σ_c , m and s values gave correlation coefficients in excess of 90%.

Figure 18 shows that the strength difference between intact material and a very tightly interlocking assemblage of particles of the same material is relatively small. It is unlikely that this degree of interlocking would exist in an in situ rock mass, except in very massive rock at considerable depth below surface. Consequently, the Mohr failure envelope for granulated marble, presented in Fig. 18, represents the absolute upper bound for jointed rock mass strength.

A more realistic assessment of the strength of heavily jointed rock masses can be made on the

basis of triaxial test data obtained in connection with the design of the slopes for the Bougainville open pit copper mine in Papua New Guinea. The results of some of these tests, carried out by Jaeger (1970), the Snowy Mountain Engineering Corporation and in the mine laboratories, have been summarized by Hoek & Brown (1980a).

The results of tests on Panguna andesite are plotted as Mohr envelopes in Fig. 19. Fig. 19(a) has been included to show the large strength difference between the intact material and the jointed rock mass. Fig. 19(b) is an enlargement of the low stress portion of Fig. 19(a), and gives details of the test results on the jointed material. Details of the materials tested are given in Table 3.

Particular mention must be made of the undisturbed 152 mm diameter core samples of jointed Panguna andesite tested by Jaeger (1970). These samples were obtained by careful triple-tube diamond core drilling in an exploration adit in the mine. They were shipped to Canberra, Australia, in the inner tubes of the core barrels, and then carefully transferred onto thin copper sheets which were soldered to form containers for the specimens. These specimens were then rubber sheathed and tested triaxially. This series of tests is, as far as the Author is aware, the most reliable set of tests ever carried out on 'undisturbed' jointed rock.

The entire Bougainville testing programme extended over a ten year period and cost several hundred thousand pounds. This level of effort was

justified because of the very large economic and safety considerations involved in designing a final slope of almost 1000 m high for one side of the open pit. Unfortunately, it is seldom possible to justify testing programmes of this magnitude in either mining or civil engineering projects, and hence the results summarized in Fig. 19 represent a very large proportion of the sum total of all published data on this subject.

A similar, although less ambitious, series of tests was carried out on a highly fractured greywacke sandstone by Raphael & Goodman (1979). The results of these tests, plotted in Fig. 20, show a much lower reduction from intact to jointed rock mass strength than for the Panguna andesite (Fig. 19). This is presumably because the intact sandstone tested by Raphael & Goodman is significantly weaker than the andesite tested by Jaeger, and hence there is less possibility of the block rotation mechanism (see Fig. 17(c)) which appears to contribute so much to the weakness of jointed systems in strong materials. This suggestion is highly speculative, and is based on intuitive reasoning rather than experimental facts.

ESTIMATING THE STRENGTH OF JOINTED ROCK MASSES

Based on their analyses of the results from tests on models, jointed rock masses and rockfill, Hoek & Brown (1980b) proposed an approximate method for estimating the strength of jointed rock masses. This method, summarized in Table 4, involves estimating the values of the empirical constants m and s from a description of the rock mass. These estimates, together with an estimate of the uniaxial compressive strength of the intact pieces of rock, can then be used to construct an approximate Mohr failure envelope for the jointed rock mass.

As a means of assisting the user in describing the rock mass, use is made of the rock mass classification systems proposed by Bieniawski (1974b) and Barton, Lien & Lunde (1974), which has been summarized by Hoek & Brown (1980a).

The Author's experience in using the values listed in Table 4 for practical engineering design suggests that they are somewhat conservative. In other words, the actual rock mass strength is higher than that estimated from the Mohr envelopes plotted from the values listed. It is very difficult to estimate the extent to which the predicted strengths are too low, since reliable field data are almost non-existent. However, based on comparisons between observed and predicted behaviour of rock slopes and underground excavations, the Author tends to regard the strength estimates made from Table 4 as lower bound values for design purposes. Obviously, in

Fig. 20. Mohr failure envelopes estimated from plotted triaxial test data (Raphael & Goodman, 1979) for highly fractured, fresh to slightly altered greywacke sandstone

Table 4. Approximate relationship between rock mass quality and material constants

Empirical failure criterion $\sigma_1' = \sigma_3' + (m\sigma_c\sigma_3' + s\sigma_c^2)^{1/2}$ σ_1' = major principal stress σ_3' = minor principal stress σ_c = uniaxial compressive strength of intact rock m, s = empirical constants	Carbonate rocks with well developed crystal cleavage, e.g. dolomite, limestone and marble	Lithified argillaceous rocks, e.g. mudstone, siltstone, shale and slate (tested normal to cleavage)	Arenaceous rocks with strong crystals and poorly developed crystal cleavage, e.g. sandstone and quartzite	Fine grained polymineralic igneous crystalline rocks, e.g. andesite, dolerite, diabase and rhyolite	Coarse grained polymineralic igneous and metamorphic crystalline rocks, e.g. amphibolite, gabbro, gneiss, granite, norite and quartzdiorite
Intact rock samples					
Laboratory size samples free from pre-existing fractures	$m = 7$ $s = 1$	$m = 10$ $s = 1$	$m = 15$ $s = 1$	$m = 17$ $s = 1$	$m = 25$ $s = 1$
Bieniawski, 1974b (CSIR)* rating	100				
Barton <i>et al.</i> , 1974 (NGI)† rating	500				
Very good quality rock mass					
Tightly interlocking undisturbed rock with rough unweathered joints spaced at 1 to 3 m	$m = 3.5$ $s = 0.1$	$m = 5$ $s = 0.1$	$m = 7.5$ $s = 0.1$	$m = 8.5$ $s = 0.1$	$m = 12.5$ $s = 0.1$
Bieniawski, 1974b (CSIR) rating	85				
Barton <i>et al.</i> , 1974 (NGI) rating	100				
Good quality rock mass					
Fresh to slightly weathered rock, slightly disturbed with joints spaced at 1 to 3 m	$m = 0.7$ $s = 0.004$	$m = 1$ $s = 0.004$	$m = 1.5$ $s = 0.004$	$m = 1.7$ $s = 0.004$	$m = 2.5$ $s = 0.004$
Bieniawski, 1974b (CSIR) rating	65				
Barton <i>et al.</i> , 1974 (NGI) rating	10				
Fair quality rock mass					
Several sets of moderately weathered joints spaced at 0.3 to 1 m, disturbed	$m = 0.14$ $s = 0.0001$	$m = 0.20$ $s = 0.0001$	$m = 0.30$ $s = 0.0001$	$m = 0.34$ $s = 0.0001$	$m = 0.50$ $s = 0.0001$
Bieniawski, 1974b (CSIR) rating	44				
Barton <i>et al.</i> , 1974 (NGI) rating	1				
Poor quality rock mass					
Numerous weathered joints at 30 to 500 mm with some gouge.	$m = 0.04$ $s = 0.00001$	$m = 0.05$ $s = 0.00001$	$m = 0.08$ $s = 0.00001$	$m = 0.09$ $s = 0.00001$	$m = 0.13$ $s = 0.00001$
Clean, compacted rockfill					
Bieniawski, 1974b (CSIR) rating	23				
Barton <i>et al.</i> , 1974 (NGI) rating	0.1				
Very poor quality rock mass					
Numerous heavily weathered joints spaced at 50 mm with gouge. Waste rock	$m = 0.007$ $s = 0$	$m = 0.010$ $s = 0$	$m = 0.015$ $s = 0$	$m = 0.017$ $s = 0$	$m = 0.025$ $s = 0$
Bieniawski, 1974b (CSIR) rating	3				
Barton <i>et al.</i> , 1974 (NGI) rating	0.01				

* CSIR Commonwealth Scientific and Industrial Research Organization.

† NGI Norway Geotechnical Institute.

Fig. 21. Simplified representation of the influence of scale on the type of rock mass behaviour model which should be used in designing underground excavations or rock slopes

designing an important structure, the user would be well advised to attempt to obtain his own test data before deciding to use strength values significantly higher than those given by Table 4.

In order to use Table 4 to make estimates of rock mass strength, the following steps are suggested:

- (a) From a geological description of the rock mass, and from a comparison between the size of the structure being designed and the spacing of discontinuities in the rock mass (see Fig. 21), decide which type of material behaviour model is most appropriate. The values listed in Table 4 should only be used for estimating the strength of intact rock or of heavily jointed rock masses containing several sets of discontinuities of similar type. For schistose rock or for jointed rock masses containing dominant discontinuities such as faults, the behaviour will be anisotropic and the strength should be dealt with in the manner described in Example 1.
- (b) Estimate the unconfined compressive strength σ_c of the intact rock pieces from laboratory test data, index values or descriptions of rock hardness (see Hoek & Bray, 1981 or Hoek & Brown, 1980a). This strength estimate is important since it establishes the scale of the Mohr failure envelope.
- (c) From a description of the rock mass or, preferably, from a rock mass classification using the system of Barton *et al.* (1974) or Bieniawski (1974b), determine the appropriate row and column in Table 4.
- (d) Using equations (6) and (7), calculate and plot a Mohr failure envelope for the estimated values of σ_c , m and s . Draw an approximate average Mohr-Coulomb linear envelope through the plotted points, and estimate the average friction angle and cohesive strength of the rock mass. Compare these values with published data for rockfill (Marachi, *et al.*, 1972; Marsal, 1967, 1973; Charles & Watts, 1980) or with data given in this Paper to ensure that the values are reasonable.
- (e) Use the estimated strength values for preliminary design purposes and carry out sensitivity studies by varying the values of m and s to determine the importance of rock mass strength in the design.
- (f) For critical designs which are found to be very sensitive to variations in rock mass strength, establish a site investigation and laboratory testing programme aimed at refining the

Fig. 22. Contours of ratio of available strength to stress in schistose rock surrounding a highly stressed tunnel

strength estimates made on the basis of the procedure outlined in the preceding steps.

EXAMPLES OF APPLICATION OF ROCK MASS STRENGTH ESTIMATES IN ENGINEERING DESIGN

In order to illustrate the application of the empirical failure criterion presented to practical engineering design problems, three examples are given. These examples have been carefully chosen to illustrate particular points and, although all of the examples are hypothetical, they are based on actual engineering problems studied by the Author.

Example 1

Figure 22 gives a set of contours of the ratio of available strength to induced stress in a schistose gneiss rock mass surrounding a tunnel. The following assumptions were made in calculating these ratios.

The vertical in situ stress in the rock surrounding the tunnel is 40 MPa, corresponding

to a depth below surface of about 1500 m. The horizontal in situ stress is 60 MPa or 1.5 times the vertical stress.

The rock strength is defined by the following constants: uniaxial compressive strength of intact rock ($\sigma_c = 150$ MPa), material constants for the isotropic rock mass ($m_i = 12.5$, $s_i = 0.1$) material constants for joint strength in direction of schistosity ($m_j = 0.28$, $s_j = 0.0001$).

The direction of schistosity is assumed to be at 40° (measured in a clockwise direction) to the vertical axis of the tunnel.

The rock mass surrounding the tunnel is assumed to be elastic and isotropic. This assumption is generally accurate enough for most practical purposes, provided that the ratio of elastic moduli parallel to and normal to the schistosity does not exceed three. In the case of the example illustrated in Fig. 22, the stress distribution was calculated by means of the two-dimensional boundary element stress analysis technique, using the programme listing published by Hoek & Brown (1980a). A modulus of elasticity

Fig. 23. Rock slope analysed in example 2 (see Table 5 for co-ordinates of slope profile, phreatic surface and failure surface)

of $E = 70$ GPa and a Poisson's ratio $\nu = 0.25$ were assumed for this analysis.

The shear and normal stresses τ and σ' , acting on a plane inclined at 40° (clockwise) to the vertical axis, were calculated for each point on a grid surrounding the tunnel. The available shear strengths in the direction of this plane, τ_{as} , were calculated by means of equations (7) and (6) (for $\sigma_c = 150$ MPa, $m_i = 0.28$ and $s_i = 0.0001$). Hence, the ratio of available shear strength τ_{as} to the induced shear stress τ was determined for each grid point.

In addition, the available strength σ_{ai}' of the isotropic rock mass was calculated at each grid point by means of equation (3), using the principal stresses σ_1' and σ_3' and the isotropic rock mass material properties ($\sigma_c = 150$ MPa, $m_i = 12.5$ and $s_i = 0.1$). This available strength σ_{ai}' was compared with the induced maximum principal stress σ_1' to obtain the ratio σ_{ai}'/σ_1' at each grid point.

In plotting the contours illustrated in Fig. 22, the lower of the two ratios τ_{as}/τ and σ_{ai}'/σ_1' was used to define the strength to stress ratio value.

The zones surrounded by the contours defined by a strength to stress ratio of one contain overstressed rock. The general method used in designing tunnels and caverns in highly stressed rock is to attempt to minimize the extent of such overstressed zones by choice of the excavation

shape and orientation in relationship to the in situ stress direction.

When zones of overstressed rock, such as those illustrated in Fig. 22, are unavoidable, appropriate support systems have to be designed in order to restrict the propagation of fracture of rock contained in these zones. Unfortunately, the analysis presented in this example cannot be used to predict the extent and direction of fracture propagation from the zones of overstressed rock and the choice of support systems tends to be based on very crude approximations.

Such approximations involve designing a system of rock bolts with sufficient capacity to support the weight of the rock contained in the overhead overstressed zones and of sufficient length to permit anchoring in the rock outside these zones.

Improved techniques for support design are being developed, but are not yet generally available for complex failure patterns such as that illustrated in Fig. 22. These techniques, discussed by Hoek & Brown (1980a), involve an analysis of the interaction between displacements, induced by fracturing in the rock surrounding the tunnel, and the response of the support system installed to control these displacements. It is hoped that these support-interaction analyses will eventually be developed to the point where they can be used to evaluate the support requirements for tunnels such

Table 5. Stability analysis of slope shown in Fig. 23

Slice	1	2	3	4	5	6	7	8	9
XT	20	135	170	288	312	450	580	660	765
YT	50	150	150	250	250	350	410	450	450
XW	20	106	162	284	308	530	635	710	765
YW	50	100	132	196	210	300	311	380	450
XB	20	82	140	274	300	580	635	710	765
YB	50	60	68	115	123	265	311	380	450
Unit weight γ : MN/m ³	0.023	0.023	0.023	0.023	0.023	0.019	0.019	0.019	Factor of safety
First iteration									
ϕ_B'	30	30	30	30	30	18	18	18	1.69
c_B'	1.0	1.0	1.0	1.0	1.0	0	0	0	
ϕ_S'	0	30	30	30	30	15	18	18	
c_S'	0	1.0	1.0	1.0	1.0	0	0	0	
σ_B'	1.32	0.77	1.40	1.57	1.89	0.58	1.38	0.54	
σ_S'	0	0.09	0.55	0.66	0.75	2.01	1.21	0.52	
Second iteration									
ϕ_B'	40.03	45.08	39.46	38.36	36.58	18	18	18	1.57
c_B'	0.48	0.32	0.51	0.55	0.64	0	0	0	
ϕ_S'	0	62.08	48.11	46.48	45.32	15	18	18	
c_S'	0	0.06	0.25	0.28	0.31	0	0	0	
σ_B'	0.74	1.07	1.31	1.76	1.96	0.57	1.37	0.53	
σ_S'	0	0.16	0.46	0.53	0.62	2.00	1.19	0.51	
Third iteration									
ϕ_B'	45.44	42.02	40.10	37.26	36.23	18	18	18	1.57
c_B'	0.31	0.41	0.48	0.61	0.66	0	0	0	
ϕ_S'	0	58.10	49.67	48.44	47.04	15	18	18	
c_S'	0	0.10	0.21	0.24	0.27	0	0	0	
σ_B'	0.74	1.07	1.31	1.76	1.96	0.57	1.37	0.53	
σ_S'	0	0.15	0.44	0.52	0.61	2.00	1.19	0.51	

as that considered in this example.

Example 2

This example involves a study of the stability of a very large rock slope such as that which would be excavated in an open pit mine. The benched profile of such a slope, having an overall angle of about 30° and a vertical height of 400 m, is shown in Fig. 23.

The upper portion of the slope is in overburden material comprising mixed sands, gravels and clays. Back-analyses of previous failures in this overburden material, assuming a linear Mohr failure envelope, give a friction angle $\phi' = 18^\circ$ and a cohesive strength $c' = 0$. The unit weight of this material averages 0.019 MN/m³.

The overburden is separated from the shale forming the lower part of the slope by a fault which is assumed to have a shear strength defined by $\phi' = 15^\circ$ and $c' = 0$.

No strength data are available for the shale, but examination of rock exposed in tunnels in this material suggests that the rock mass can be rated

as 'good quality'. From Table 4, the material constants $m = 1$ and $s = 0.004$ are chosen as representative of this rock. In order to provide a measure of conservatism in the design, the value of s is downgraded to zero to allow for the influence of stress relaxation which may occur as the slope is excavated. The strength of the intact material is estimated from point load tests (see Hoek & Brown, 1980a) as 30 MPa. The unit weight of the shale is 0.023 MN/m³.

The phreatic surface in the rock mass forming the slope, shown in Fig. 23, is estimated from general knowledge of the hydrogeology of the site and from observations of seepage in tunnels in the slope.

Analysis of the stability of this slope is carried out by means of the non-vertical slice method (Sarma, 1979). This method is ideally suited to many rock slope problems because it permits the incorporation of specific structural features such as the fault illustrated in Fig. 23. This analysis has been slightly modified by the Author, and the equations used in the examples are listed in

Fig. 24. Mohr circles derived from drained triaxial tests on retorted oil shale waste

Fig. 25. Analyses of active-passive wedge failure in waste dumps of retorted oil shale resting on weak foundations. (a) Mohr-Coulomb failure criterion, factor of safety = 1.41; (b) Hoek-Brown failure criterion, factor of safety = 1.08

Appendix 2.

Table 5 lists the co-ordinates of the slope profile (XT, YT), the phreatic surface (XW, YW), and the base or failure surface (XB, YB) which was found, from a number of analyses, to give the lowest factor of safety. As a first approximation, the strength of the shale is assumed to be defined by $\phi' = 30^\circ$ and $c' = 1$ MPa. Analysis of the slope, using these values, gives a factor of safety of 1.69.

The effective normal stresses σ'_b and σ'_s on the slice bases and sides, respectively, are calculated during the course of this analysis and these values are listed, for each slice, in Table 5. These values are used to determine appropriate values for the instantaneous friction angle ϕ'_i and instantaneous cohesive strength c'_i for the shale by means of equations (6) and (7) (for $\sigma_c = 30$ MPa, $m = 1$ and $s = 0$). These values of ϕ'_i and c'_i are used in the second iteration of a stability analysis and, as shown in Table 5, the resulting factor of safety is 1.57.

This process is repeated a third time, using values of ϕ'_i and c'_i calculated from the effective normal stresses given by the second iteration. The factor of safety given by the third iteration is 1.57. An additional iteration, not included in Table 5, gave the same factor of safety and no further iterations were necessary.

This example is typical of the type of analysis which would be carried out during the feasibility or the basic design phase for a large open pit mine or excavation for a dam foundation or spillway. Further analyses of this type would normally be carried out at various stages during excavation of the slope as the rock mass is exposed and more reliable information becomes available. In some cases, a testing programme may be set up to attempt to investigate the properties of materials such as the shale forming the base of the slope shown in Fig. 23.

Example 3

A problem which frequently arises in both mining and civil engineering projects is that of the stability of waste dumps on sloping foundations. This problem has been studied extensively by the Commonwealth Scientific and Industrial Research Organization in Australia in relation to spoil pile failures in open cast coal mines (see, for example, Coulthard, 1979). These studies showed that many of these failures involved the same active-passive wedge failure process analysed by Seed & Sultan (1967, 1969) and Horn & Hendron (1968) for the evaluation of dams with sloping clay cores.

In considering similar problems, the Author has found that the non-vertical slice method published by Sarma (1979) is well suited to an analysis of this active-passive wedge failure. Identical results to

those obtained by Coulthard (1979) are given by assuming a drained spoil pile with a purely frictional shear strength on the interface between the active and passive wedges. However, Sarma's method also allows the analysis of a material with non-linear failure characteristics and, if necessary, with ground water pressures in the pile.

The example considered here involves a 75 m high spoil pile with a horizontal upper surface and a face angle of 35° . The unit weight of the spoil material is 0.015 MN/m³. This pile rests on a weak foundation inclined at 12° to the horizontal. The shear strength of the foundation surface is defined by a friction angle of $\phi' = 15^\circ$ and zero cohesion. The pile is assumed to be fully drained.

Triaxial tests on retorted oil shale material forming the soil pile give the Mohr circles plotted in Fig. 24. Regression analysis of the triaxial test data, assuming a linear Mohr failure envelope, gave $\phi' = 29.5^\circ$ and $c' = 0.205$ MPa with a correlation coefficient of 1. Analysis of the same data, using the 'broken rock' analysis given in Appendix 1, for $\sigma_c = 25$ MPa (determined by point load testing) gave $m = 0.243$ and $s = 0$. Both linear and non-linear Mohr failure envelopes are plotted in Fig. 24, and both of these envelopes will be used for the analysis of spoil pile stability.

Figure 25 gives the results of stability analyses for the Mohr-Coulomb and Hoek-Brown failure criteria. These analyses were carried out by optimizing the angle of the interface between the active and passive wedge, followed by the angle of the back scarp followed by the distance of the back scarp behind the crest of the spoil pile. In each case, these angles and distances were varied to find the minimum factor of safety in accordance with the procedure suggested by Sarma (1979).

The factor of safety obtained for the Mohr-Coulomb failure criterion ($\phi' = 29.5^\circ$ and $c' = 0.205$ MPa) was 1.41, while that obtained for the Hoek-Brown criterion ($\sigma_c = 25$ MPa, $m = 0.243$ and $s = 0$) was 1.08. In studies on the reason for the difference between these two factors of safety, it was found that the normal stresses acting across the interface between the active and passive wedges and on the surface forming the back scarp range from 0.06 to 0.11 MPa. As can be seen from Fig. 24, this is the normal stress range in which no test data exists and where the linear Mohr-Coulomb failure envelope, fitted to test data at higher normal stress levels, tends to over-estimate the available shear strength.

This example illustrates the importance of carrying out triaxial or direct shear tests at the effective normal stress levels which occur in the actual problem being studied. In the example considered here, it would have been more appropriate to carry out a preliminary stability analysis,

based on assumed parameters, before the testing programme was initiated. In this way, the correct range of normal stresses could have been used in the tests. Unfortunately, as frequently happens in the real engineering world, limits of time, budget and available equipment means that it is not always possible to achieve the ideal testing and design sequence.

CONCLUSION

An empirical failure criterion for estimating the strength of jointed rock masses has been presented. The basis for its derivation, the assumptions made in its development, and its advantages and limitations have all been discussed. Three examples have been given to illustrate the application of this failure criterion in practical geotechnical engineering design.

From this discussion and from some of the questions left unanswered in the examples, it will be evident that a great deal more work remains to be done in this field. A better understanding of the mechanics of jointed rock mass behaviour is a problem of major significance in geotechnical engineering, and it is an understanding to which both the traditional disciplines of soil mechanics and rock mechanics can and must contribute. The Author hopes that the ideas presented will contribute toward this understanding and development.

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APPENDIX 1. DETERMINATION OF MATERIAL CONSTANTS FOR EMPIRICAL FAILURE CRITERION

Failure criterion

The failure criterion defined by equation (3)

$$\sigma_1' = \sigma_3' + (m\sigma_c \sigma_3' + s\sigma_c^2)^{1/2} \quad (3)$$

can be rewritten as

$$y = m\sigma_c x + s\sigma_c^2 \quad (16)$$

where $y = (\sigma_1' - \sigma_3')^2$ and $x = \sigma_3'$

Intact rock

For intact rock, $s = 1$ and the uniaxial compressive strength σ_c and the material constant m are given by

$$\sigma_c^2 = \frac{\Sigma y}{n} - \left[\frac{\Sigma xy - \frac{\Sigma x \Sigma y}{n}}{\Sigma x^2 - \frac{(\Sigma x)^2}{n}} \right] \frac{\Sigma x}{n} \quad (17)$$

$$m = \frac{1}{\sigma_c} \left[\frac{\Sigma xy - \frac{\Sigma x \Sigma y}{n}}{\Sigma x^2 - \frac{(\Sigma x)^2}{n}} \right] \quad (18)$$

The coefficient of determination r^2 is given by

$$r^2 = \frac{(\Sigma xy - \Sigma x \Sigma y/n)^2}{(\Sigma x^2 - (\Sigma x)^2/n)(\Sigma y^2 - (\Sigma y)^2/n)} \quad (19)$$

Broken rock

For broken or heavily jointed rock, the strength of the intact rock pieces is determined by the analysis given above. The value of the constant m for broken or heavily jointed rock is found from equation (18). The value of the constant s is given by

$$s = \frac{1}{\sigma_c^2} \left[\frac{\Sigma y}{n} - m\sigma_c \frac{\Sigma x}{n} \right] \quad (20)$$

The coefficient of determination is found from equation (19).

When the value of s is very close to zero, equation (20) will sometimes give a small negative value. In such cases, put $s = 0$ and calculate the constant m as follows

$$m = \frac{\Sigma y}{\sigma_c \Sigma x} \quad (21)$$

When equation (21) is used, equation (19) is not valid.

Mohr envelope

The Mohr failure envelope is defined by the following equation, derived by Dr J. Bray of Imperial College

$$\tau = (\cot \phi_i' - \cos \phi_i') \frac{m\sigma_c}{8} \quad (22)$$

where the instantaneous friction angle ϕ_i' is given by

$$\phi_i' = \text{Arctan} \left(4h \cos^2 \left(30 + \frac{1}{3} \text{Arcsin } h^{-2/3} \right) - 1 \right)^{-1/2} \quad (23)$$

where

$$h = 1 + \frac{16(m\sigma' + s\sigma_c)}{3m^2 \sigma_c}$$

and the instantaneous cohesive strength c_i' is given by

$$c_i' = \tau - \sigma' \tan \phi_i' \quad (24)$$

where σ' is the effective normal stress.

Determination of m and s from direct shear test data

The following method for determination of the material constants m and s from direct shear test data was devised by Dr S. Dunbar (unpublished report) of Golder Associates in Vancouver.

Fig. 26. Geometry of and forces acting on a single slice in the Sarma (1979) non-vertical method for stability analysis

The major and minor principal stresses σ_1' and σ_3' corresponding to each τ, σ' pair can be calculated as follows

$$\sigma_1' = \frac{(\sigma'^2 + (\tau - c')\tau) + \tau(\sigma'^2 + (\tau - c')^2)^{1/2}}{\sigma'} \quad (25)$$

$$\sigma_3' = \frac{(\sigma'^2 + (\tau - c')\tau) - \tau(\sigma'^2 + (\tau - c')^2)^{1/2}}{\sigma'} \quad (26)$$

where c' is an estimate of the cohesion intercept for the entire τ, σ' data set. This estimate can be an assumed value greater than or equal to zero or it can be determined by linear regression analysis of the shear test results.

After the calculation of the values of σ_1' and σ_3' by means of equations (25) and (26), the determination of the material constants m and s is carried out as for broken rock.

An estimate of the uniaxial compressive strength σ_c of the intact rock is required in order to complete the analysis.

APPENDIX 2. SARMA NON-VERTICAL SLICE METHOD FOR THE ANALYSIS OF SLOPE FAILURE ON SURFACES OF GENERAL SHAPE

Introduction

This analysis, published by Sarma (1979), is a general method of limit equilibrium analysis which can be used to determine the stability of slopes of a variety of shapes. Slopes with complex profiles sliding on circular, non-circular or plane surfaces or any combination of such surfaces can usually be analysed by this method. In addition, active-passive wedge failures such as those which occur in spoil piles on sloping foundations or in clay core embankments can also be analysed. The analysis allows different shear strengths (defined by cohesion and angle of friction) to be specified for each slice base and side. The freedom to change the inclination of the sides of the slice also allows the incorporation of specific structural features such as faults. Water pressures acting on the sides and base of each slice are included in the analysis. External forces due to water pressure in tension cracks or to reinforcement installed in the slope can be incorporated but have not been included in this version.

The geometry of the sliding mass is defined by the coordinates of the corners of a number of three- or four-sided elements. The phreatic surface is defined by the coordinates of its intersections with the slice sides. A closed form solution is then used to calculate the critical horizontal acceleration K_c required to induce a state of limiting equilibrium in the slope. The static factor of safety of the slope is then found by reducing the values of $\tan \phi$ and c to $\tan \phi/F$ and c/F (where F is the factor of safety) until $K_c = 0$.

In order to determine whether the analysis is acceptable, a final check is carried out to assess whether all the effective normal stresses acting across the bases and sides of the slices are positive. If negative stresses are found, the slice geometry must be varied until these negative stresses are eliminated. An additional check on moment equilibrium is also recommended for critical slopes.

The equations listed here have been arranged for

programming on a Hewlett Packard 41CV calculator and a full analysis (excluding the moment equilibrium check) can be carried out for ten slices. These equations differ slightly from those published by Sarma (1979) in that a more complete equation is used for the calculation of the effective normal stress on the slice base. This calculation is essential for the analysis of failure of slopes in materials with a non-linear failure criterion.

Geometrical calculations

The geometry of the i th slice is defined in Fig. 26. Assuming that ZW_i , δ_i and d_i are available from the previous slice

$$d_{i+1} = ((X T_{i+1} - X B_{i+1})^2 + (Y T_{i+1} - Y B_{i+1})^2)^{1/2} \quad (27)$$

$$\delta_{i+1} = \text{Arcsin}((Y T_{i+1} - Y B_{i+1})/d_{i+1}) \quad (28)$$

$$b_i = X B_{i+1} - X B_i \quad (29)$$

$$\alpha_i = \text{Arctan}((Y B_{i+1} - Y B_i)/b_i) \quad (30)$$

$$W_i = \frac{1}{2}\gamma((Y B_i - Y T_{i+1})(X T_i - X B_{i+1}) + (Y T_i - Y B_{i+1})(X T_{i+1} - X B_i)) \quad (31)$$

$$ZW_{i+1} = (Y W_{i+1} - Y B_{i+1}) \quad (32)$$

Calculation of water forces

$$U_i = \frac{1}{2}\gamma_w(ZW_i + ZW_{i+1})b_i \sec \alpha_i \quad (33)$$

$$PW_i = \frac{1}{2}\gamma_w ZW_i^2 \sec \delta_i \quad (34)$$

$$PW_{i+1} = \frac{1}{2}\gamma_w ZW_{i+1}^2 \sec \delta_{i+1} \quad (35)$$

where γ and γ_w are the unit weights of rock and water respectively.

Calculation of critical acceleration K_c

$$K_c = \frac{a_n + a_{n-1} \cdot e_n + a_{n-2} \cdot e_n \cdot e_{n-1} + \dots + a_1 \cdot e_n \cdot e_{n-1} \dots e_3 e_2}{p_n + p_{n-1} \cdot e_n + p_{n-2} \cdot e_n \cdot e_{n-1} + \dots + p_1 \cdot e_n \cdot e_{n-1} \dots e_3 e_2} \quad (36)$$

where

$$a_i = Q_i(W_i \cdot \sin(\phi_{Bi} - \alpha_i) + R_i \cdot \cos \phi_{Bi} + S_{i+1} \cdot \sin(\phi_{Bi} - \alpha_i - \delta_{i+1}) - S_i \cdot \sin(\phi_{Bi} - \alpha_i - \delta_i)) \quad (37)$$

$$p_i = Q_i \cdot W_i \cdot \cos(\phi_{Bi} - \alpha_i) \quad (38)$$

$$e_i = Q_i(\cos(\phi_{Bi} - \alpha_i + \phi_{Si} - \delta_i) \sec \phi_{Si}) \quad (39)$$

$$Q_i = \sec(\phi_{Bi} - \alpha_i + \phi_{Si+1} - \delta_{i+1}) \cdot \cos \phi_{Si+1} \quad (40)$$

$$S_i = (c_{Si} \cdot d_i - PW_i \cdot \tan \phi_{Si}) \quad (41)$$

$$S_{i+1} = (c_{Si+1} \cdot d_{i+1} - PW_{i+1} \cdot \tan \phi_{Si+1}) \quad (42)$$

$$R_i = (c_{Bi} \cdot b_i \cdot \sec \alpha_i - U_i \cdot \tan \phi_{Bi}) \quad (43)$$

Calculation of factor of safety F

For slopes where $K_c \neq 0$, the factor of safety is calculated by reducing the shear strength simultaneously on all sliding surfaces until the acceleration K calculated by means of equation (36) is equal to zero. This is achieved by substitution, in equation (37) to (43) of the following shear strength values

$$c_{Bi}/F, \quad \tan \phi_{Bi}/F, \quad c_{Si}/F, \\ \tan \phi_{Si}/F, \quad c_{Si+1}/F \quad \text{and} \quad \tan \phi_{Si+1}/F$$

Check on acceptability of solution

Having determined the value of K for a given factor of safety, the forces acting on the sides and bases of the slices are found by progressive solution of the following equations, starting from the known condition that $E_1 = 0$.

$$E_{i+1} = a_i - p_i \cdot K + E_i \cdot e_i \quad (44)$$

$$X_i = (E_i - PW_i) \tan \phi_{Si} + c_{Si} \cdot d_i \quad (45)$$

$$N_i = (W_i + X_{i+1}) \cdot \cos \delta_{i+1} - X_i \cdot \cos \delta_i \\ - E_{i+1} \cdot \sin \delta_{i+1} + E_i \cdot \sin \delta_i \\ + U_i \cdot \tan \phi_{Bi} \cdot \sin \alpha_i - c_{Bi} \cdot b_i \cdot \tan \alpha_i \\ \times \cos \phi_{Bi} \cdot \sec (\phi_{Bi} - \alpha_i) \quad (46)$$

$$T_i = (N_i - U_i) \tan \phi_{Bi} + c_{Bi} \cdot b_i \cdot \sec \alpha_i \quad (47)$$

The effective normal stresses acting across the base and the sides of a slice are calculated as follows

$$\sigma_{Bi}' = (N_i - U_i)/b_i \cdot \sec \alpha_i \quad (48)$$

$$\sigma_{Si}' = (E_i - PW_i)/d_i \quad (49)$$

$$\sigma_{Si+1}' = (E_{i+1} - PW_{i+1})/d_{i+1} \quad (50)$$

In order for the solution to be acceptable, all effective normal stresses must be positive.

A final check recommended by Sarma is for moment equilibrium. Referring to Fig. 26 and taking moments about the lower left hand corner of the slice

$$N_i l_i - X_{i+1} \cdot b_i \cdot \sec \alpha_i \cdot \cos (\alpha_i + \delta_{i+1}) \\ - E_i Z_i + E_{i+1} (Z_{i+1} + b_i \cdot \sec \alpha_i \cdot \sin (\alpha_i + \delta_{i+1})) \\ - W_i (XG_i - X_{Bi}) + K_c W_i (YG_i - Y_{Bi}) = 0 \quad (51)$$

where XG_i , YG_i are the co-ordinates of the centre of gravity of the slice.

Starting from the first slice, where $Z_1 = 0$, assuming a value for l_i , the moment arm Z_{i+1} can be calculated or vice versa. The values of Z_i and Z_{i+1} should lie within the slice boundary, preferably in the middle third.

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VOTE OF THANKS

In proposing a vote of thanks to Dr Hoek, Professor R. E. Gibson said: 'We have listened to a discourse aimed, in the lecturer's own words,

“... at providing a better understanding of the mechanics of jointed rock mass behaviour: a problem of major significance in geotechnical engineering”. To those academics among us who have given attention to this problem, it is recognized as one of great difficulty and fascination. To those practising engineers who are obliged to arrive at decisions based on whatever data and understanding they possess, it can be a daunting responsibility. Evert Hoek's wide-ranging career has given him an unusual understanding and appreciation of both these viewpoints so that he perceives what the engineer needs from research

and also the extent to which the uncertainties inherent in nature allow this need to be met.

‘Dr Hoek has spoken with authority on a subject of great importance to all geotechnical engineers and has succeeded brilliantly in his aim of providing a better understanding of the mechanics of jointed rock. I am sure that in the future this Lecture will be referred to many times.

‘I should like on behalf of us all to congratulate Dr Hoek most warmly on his splendid lecture and to propose now a hearty vote of thanks to him’.

The vote of thanks was accorded with acclamation.